

Supplemental Material: Deep decoupling in subduction zones: observations and temperature limits

Geoffrey A. Abers¹, Peter E. van Keken², Cian R. Wilson²

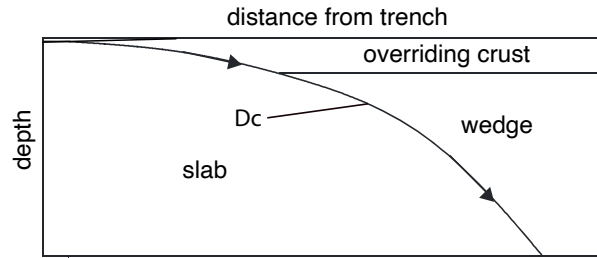
¹Department of Earth and Atmospheric Sciences, Cornell University, Ithaca NY 14853, U.S.A.

²Earth and Planets Laboratory, Carnegie Institution for Science, Washington DC 20015, U.S.A.

1. NUMERICAL METHODS

In this section we provide further details of the numerical model setup from Section 3.3 including the equations and boundary conditions as well as providing details on how the input files used can be accessed and run.

1.1 Domain and equations



The model domain is divided into three regions: the overriding crust, the mantle wedge, and the slab. We solve separately for the velocity and pressure in the wedge and the velocity and pressure in the slab assuming the incompressible Stokes equation

$$-\nabla \cdot (2\eta \dot{\epsilon}_i) + \nabla p_i = 0 \quad (S1)$$

$$\nabla \cdot \mathbf{v}_i = 0 \quad (S2)$$

where η is the viscosity and $\dot{\epsilon}_i$ is the strain-rate tensor

$$\dot{\epsilon}_i = \left(\frac{\nabla \mathbf{v}_i + \nabla \mathbf{v}_i^T}{2} \right) \quad (S3)$$

(\mathbf{v}_i, p_i) are the velocity and pressure in the slab, (\mathbf{v}_s, p_s) , or in the wedge, (\mathbf{v}_w, p_w) . The velocity in the overriding crust \mathbf{v}_c is assumed to be $(0,0)$.

Flow is driven in the slab and wedge using an internal boundary condition along the slab surface, separating the slab from the overriding crust and wedge. On the slab side this drives \mathbf{v}_s at the convergence rate V parallel to the slab surface along its entire length. On the wedge side the boundary condition for \mathbf{v}_w is $(0,0)$ down to the coupling depth, D_c (80 km, unless otherwise stated). It then ramps up linearly to have magnitude V parallel to the slab surface over an interval of 2.5 km. $\mathbf{v}_w = (0,0)$ along the Moho, separating the wedge from the overriding crust. All other external boundaries of the domain have zero stress (zero Neumann) boundary conditions.

Viscosity, η , follows a dry olivine rheology, η_{ol} , with a maximum viscosity cap, η_{max} , such that

$$\eta = \left(\frac{1}{\eta_{ol}} + \frac{1}{\eta_{max}} \right)^{-1} \quad (S4)$$

$$\eta_{ol} = A_{ol} \exp \left(\frac{E_{ol}}{n_{ol}RT} \right) \dot{\epsilon}_{IIi}^{\frac{(1-n_{ol})}{n_{ol}}} \quad (S5)$$

$$\dot{\epsilon}_{IIi} = \left(\frac{\dot{\epsilon}_i \cdot \dot{\epsilon}_i}{2} \right)^{\frac{1}{2}} \quad (S6)$$

where A_{ol} , E_{ol} , R , and n_{ol} are the pre-exponential constant, activation energy, gas constant and power-law exponent respectively (see Table S1). Parameters follow Karato and Wu (1993).

TABLE S1: CONSTANT EQUATION PARAMETERS

A_{ol}	pre-exponential constant – dry olivine	28968.6	$\text{Pa s}^{1/n_{ol}}$
E_{ol}	activation energy – dry olivine	540	kJ / mol
R	gas constant	8.3145	J / mol / K
n_{ol}	power-law exponent – dry olivine	3.5	
η_{max}	maximum viscosity cap	10^{25}	Pa s
ρ_w, ρ_s	mantle (wedge & slab) density	3300	kg m^{-3}
c_p	isobaric heat capacity	1250	J / kg / K
k_w, k_s	mantle (wedge & slab) thermal conductivity	3.1	W / m / K
w	shear zone width	500	m
a_{H_2O}	water activity	1	
A_{f1}	water fugacity pre-exponential	5521	MPa
A_{f2}	water fugacity activation energy	31.28	kJ / mol
A_{f3}	water fugacity activation volume	-2.009×10^{-5}	m^3 / mol
T_m	mantle potential temperature	1350	$^{\circ}\text{C}$
$(dT/dz)_a$	adiabatic temperature gradient	0.3	$^{\circ}\text{C/km}$

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41 We find the temperature neglecting compressible effects, T^* , by solving the heat equation
42 on the whole domain

$$\rho_i c_p \mathbf{v}_i \cdot \nabla T^* - \nabla \cdot (k_i \nabla T^*) - Q_i - \delta_f H = 0 \quad (S7)$$

44 where ρ_i and k_i are the density and thermal conductivity of the overriding crust (ρ_c, k_c), mantle
45 wedge (ρ_w, k_w) and slab (ρ_s, k_s), and c_p is the isobaric heat capacity. Q_i is the radiogenic heat
46 production, which is zero in the mantle wedge and slab ($Q_w = Q_s = 0$). Non-zero heating in the
47 overriding crust is varied between the lower crust, Q_{lc} , and the upper crust, Q_{uc} (see Table S2).
48 Shear heating, H , is applied only along the slab surface, as indicated by the delta-function, $\delta_f =$
49 $\delta(\mathbf{s} - \mathbf{s}_f)$ where \mathbf{s} is the position vector and \mathbf{s}_f is the position of the slab surface. H is defined
50 following (2)

$$H = V_f \tau \quad (S8)$$

$$\tau = \tau_v \tanh \left(\frac{\tau_f}{\tau_v} \right) \quad (S9)$$

$$\tau_f = \mu' \sigma_n \quad (\text{S10})$$

$$\sigma_n = \begin{cases} z \rho_c g, & z \leq \Delta z_c \\ (z - \Delta z_c) \rho_s g + \Delta z_c \rho_c g, & z > \Delta z_c \end{cases} \quad (\text{S11})$$

$$\tau_v = \frac{1}{2} B^{-1/n} \left(\frac{V_f}{w} \right)^{1/n} f_{H_2O}^{-r/n} \exp \left(\frac{E + \sigma_n V^*}{nRT} \right) \quad (\text{S12})$$

$$f_{H_2O} = a_{H_2O} A_{f_1} \exp \left(-\frac{A_{f_2} + \sigma_n A_{f_3}}{RT} \right) \quad (\text{S13})$$

V_f is the magnitude of the velocity jump across the slab surface, $\|\mathbf{v}_w - \mathbf{v}_s\|_f$, so follows the velocity internal boundary condition starting at the trench at the full convergence rate V before linearly decreasing to zero over a 2.5 km depth interval after the coupling depth, D_c , is reached (at 80 km unless otherwise stated). τ_f is the frictional stress resulting from the friction coefficient, μ' , and fault-normal stress, σ_n , assumed equal to lithostatic pressure. In (S11) z is the depth below the surface (taking bathymetry into account), g is the magnitude of the acceleration due to gravity, and Δz_c is the crustal thickness. τ_v is the differential stress in a ductile shear zone of width w , where f_{H_2O} is an approximation to water fugacity (Shinevar et al., 2015) and B , n , r , E and V^* are laboratory-derived flow parameters specific to the assumed rheology (see Table S3). a_{H_2O} , A_{f_1} , A_{f_2} and A_{f_3} are the water activity and other constants related to the water fugacity law (see Table S1).

Since we have simplified the modeling to neglect the effect of compression (which is what causes the adiabat) it is useful, when comparing our model results to natural conditions at depth, to add the adiabatic heating effect such that:

$$T = T^* + \left(\frac{dT}{dz} \right)_a z \quad (\text{S14})$$

where $(dT/dz)_a = 0.3^\circ\text{C}/\text{km}$ is the assumed linear adiabatic gradient added *a posteriori* to the model temperature, T^* , to reconstruct the full temperature, T , used in (S12), (S13) and (S5) and presented in all figures and results.

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TABLE S2: CASE-DEPENDENT PARAMETERS

		Idealized	Alaska Peninsula	Nicaragua	N. Honshu	WA Cascades	units
<u>Thermal model parameters</u>							
ρ_c	crustal density	3300	2750	2750	2750	2750	kg m ⁻³
k_c	crustal thermal conductivity	3.1	2.5	2.5	2.5	2.5	W/m/K
Q_{uc}	upper crust heat production	0	1.3	1.3	1.3	1.3	$\mu\text{W m}^{-3}$
Q_{lc}	lower crust heat production	0	0.27	0.27	0.27	0.27	$\mu\text{W m}^{-3}$
Δz_{uc}	upper crust thickness	20	15	15	15	15	km
Δz_c	total crust thickness	50	35	30	40	40	km
<u>H₂O flux parameters</u>							
	Sediment thickness (trench)	0	0.8	0.5	0.6	2.5	km
	Sediment thickness (≥ 15 km depth)	0	0.4	0.3	0.3	0.4	km
	Sediment type	–	turbidite	carbonate	diatom ooze	pelagic	<i>Table S5</i>
	Domain depth	230	240	240	240	290	km
	Domain width	$230/\tan(\Delta)$ + 20	412	255	560	586	km

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The temperature neglecting adiabatic effects is found using a halfspace cooling model as a boundary condition on the left-hand, slab side of the domain. A mantle potential temperature, T_m , of 1350°C is assumed. On the right-hand, wedge and overriding crust side of the domain a continental geotherm based on a surface heat flow of 65 mW/m² is applied using the analytical solution of the 1D heat equation with heat production in the upper and lower crust, Q_{uc} and Q_{lc} . The right-hand boundary condition is capped at T_m . Zero Dirichlet and Neumann boundary conditions are applied to the top and bottom of the domain respectively.

TABLE S3: RHEOLOGY-DEPENDENT PARAMETERS

		WETQZ	WETOLV	WESTERLY	SERP	BIOTI	MUSC	units
B	ductile flow pre-exponential	6.31×10^{-12}	1.58×10^3	2×10^{-4}	2.82×10^{-15}	1.2×10^{-30}	9.8×10^6	$\text{MPa}^{-(n+r)}/s$
n	ductile flow stress exponent	4	3.5	1.9	3.8	18	1.13	
r	ductile flow water fugacity exponent	1	1.2	0	0	0	0	
E	ductile flow activation energy	135	520	141	8.9	51	270	kJ/mol
V^*	ductile flow activation volume	0	2.2×10^{-5}	0	3.2×10^{-6}	0	0	m^3/mol
	reference	Hirth et al. (2001)	Hirth and Kohlstedt (2003)	Hansen and Carter (1983)	Hilalret et al. (2007)	Kronenberg et al. (1990)	Mariani et al. (2007)	

1.2 Discretization and solution

The equations are non-dimensionalized then discretized using finite elements on a mesh composed of triangular cells. We use the Taylor-Hood element pair for the Stokes equations (S1, S2), with piecewise quadratic polynomials for velocity, \mathbf{v}_s and \mathbf{v}_w , and piecewise linear polynomials for pressure, p_s and p_w . The temperature is discretized using piecewise quadratic polynomials. All polynomials are continuous across elements.

The solution procedure begins by finding the solution to the Stokes (S1, S2) and heat (S7) equations assuming an isoviscous rheology, $\eta = \text{constant}$, and with no shear heating, $H = 0$. This provides an initial guess to solve the full equations, for which an outer Picard iteration is applied to resolve the nonlinearities between the Stokes and heat equations. An inner Newton iteration is used to solve the nonlinearities arising from shear heating within the heat equation.

1.3 Software and input files

1.3.1 Underlying software

All numerical simulations are constructed and run with the finite element model builder TerraFERMA (Transparent Finite Element Rapid Model Assembler; Wilson et al., 2017). This utilizes the open source numerical software packages PETSc (<https://www.mcs.anl.gov/petsc>) for linear algebra and FEniCS (<https://fenicsproject.org>) for finite element code generation.

1.3.2 Software availability: Docker version

Interested users can access the modeling software, together with all model inputs and equations parameters, and reproduce the models presented here using Docker (<https://www.docker.com>). Once Docker is installed one can simply download the software and create a run-time environment by typing in a shell (called ‘Terminal’ in MacOS):

```
docker run -it --rm cianwilson/abers_geosphere_2020
```

This opens up a window into a Linux environment with a command line prompt. A description of the functionality of the software, run-time options, and overview of the output is provided in the README.md that is in the present directory and can also be found at https://hub.docker.com/r/cianwilson/abers_geosphere_2020. There are some modifications that need to be made to the default settings described above to make the software fully functional. Changes need to be made to i) allow for sharing files between the special Linux environment and the host computer; and ii) to allow for graphics to be used. The changes can be made by additional options on the command line and instructions are provided in the README.md file.

1.3.3 Software availability: as add-on to an existing TerraFERMA installation

We recommend running the simulations through the docker image to ensure compatible versions are used, but if an installation of TerraFERMA is available then all the simulation input is available in a git repository, available at: https://bitbucket.org/cwilson/abers_geosphere_2020. Assuming a working installation of git, this can be downloaded at the command line using the command:

```
git clone https://bitbucket.org/cwilson/abers_geosphere_2020
```

The input files, available through both Docker and git, have extensions “.tfml” and contain a full description of the problem including the equations, coefficients, boundary conditions and solution algorithms. Full instructions on manually installing and using TerraFERMA are available at: <http://terraferma.github.io>.

1.4 Summary of attenuation studies

TABLE S4. REGIONAL-EARTHQUAKE Q STUDIES ACROSS FOREARC AND ARC MANTLE

Arc segment ⁽¹⁾	Slab depth below Q boundary	What is measured ⁽²⁾	Reference
Alaska	80 km	$Q_P, Q_S \alpha = 0, 0.27$	Stachnik et al., 2004
Nicaragua, Costa Rica	80 km	$Q_P, Q_S \alpha = 0, 0.27$	Rychert et al., 2008
Andes 21-24°S	85–110 km	$Q_P; \alpha = 0$	Schurr et al., 2003; 2006
Hikurangi	75–85 km	$Q_P, Q_S; 10 \text{ Hz}; \alpha = 0$	Eberhart-Phillips et al., 2008; 2020
Tonga 19-22°S	80 km	$Q_P; \alpha = 0.27$	Wei & Wiens, 2018
N. Honshu	80–100 km	$Q_P; \alpha = 0.27$	Nakajima et al., 2013
		$Q_P, Q_S; \alpha = 0.27$	Liu et al., 2014
Hokkaido	~ 80 km	$Q_P; \alpha = 0.27$	Kita et al., 2014
Central Java	~100 km ?	$Q_P; \alpha = 0$	Bohm et al., 2013
Aegean	65–85 km?	$Q_P, Q_S; \alpha = 0$	Ventouzi et al., 2018
N. Marianas	Unclear	Q_P , limited $Q_S; \alpha = 0.27$	Pozgay et al., 2009
Kyushu	No high- Q forearc	$Q_P, Q_S; \alpha = 0.27$	Liu & Zhao, 2015; Saita et al., 2015
S. Peru	No high- Q forearc or flat slab	$Q_P, Q_S; \alpha = 0.27$	Jang et al., 2019
Mexico	Unusual geometry	$Q_P, \alpha = 0.0$	Chen & Clayton, 2008

⁽¹⁾ includes only studies that image the mantle to at least 100 km depth and that use body-wave methods described in the text.

⁽²⁾ α is frequency-dependence exponent where Q_i is parameterized as $Q_{i0}f^\alpha$ for phase $i = P$ or S ; reported values refer to Q_i at 1.0 Hz.

1.5 H₂O flux calculations

Following the generation of thermal models, the hydration state of the descending plate is calculated following the approach of van Keken et al. (2011). To estimate the H₂O concentration as a function of pressure and temperature, the descending plate is discretized into layers described in Table S5, with a sediment type and thickness chosen specific to a region following van Keken et al. (2011) and reproduced in Table S2. Although these parameters and the related bulk compositions have been published previously, they are accumulated here for completeness in Table S5. From these bulk compositions the phase equilibria are generated using Perple_X (Connolly, 2005) version 6.8.9 of 15 March 2020 (<https://www.perplex.ethz.ch>), using the hp622ver.dat thermodynamic database (Holland and Powell, 2011). The solution models follow those tabulated by Hacker (2008).

TABLE S5: LITHOLOGY AND COMPOSITION OF THE SUBDUCTING PLATE

Lithology or layer	SiO ₂ wt%	TiO ₂ wt%	Al ₂ O ₃ wt%	Cr ₂ O ₃ wt%	FeO wt%	MnO wt%	MgO wt%	CaO wt%	Na ₂ O wt%	K ₂ O wt%	H ₂ O wt%	CO ₂ wt%	thickness km
<u>Sediment⁽¹⁾</u>													
carbonate	13.3	0	0.7		3.7		1.3	44.5	0.4	0.3	0.5	34.5	var. ⁽²⁾
chert	88.7	0.1	2.3		1.3	0.3	0.7	0.4	0.5	0.6	0.8		var.
terrigenous diatom ooze	55.2	0.9	20.8		6	0.1	2.2	0.5	0.6	3.0	5.2		var.
pelagic	70.8	0.5	12.2		4.9		2.2	0.7	3.5	2.3	2.3		var.
turbidite	49.8	0.6	14.7		7.3	2.1	3.1	3.5	3.1	3.6	6.5		var.
	57.9	0.8	15.4		6		3	2.4	2.9	2.4	9.2		var.
<u>Hydrated crust by layer⁽³⁾</u>													
upper volcanics	50.6	1.5	15.7		10.6		7.6	11.1	2.6	0.5	5.3	2.7	0.3
lower volcanics	50.6	1.5	15.7		10.6		7.6	11.1	2.6	0.3	3.5	2.0	0.3
dikes	50.6	1.5	15.7		10.6		7.6	11.1	2.6	0.14	1.76	0.14	1.4
gabbro	50.6	0.9	16.1		6.2		9.2	12.5	2.8	0.05	0.79	0.02	5.0
mantle ⁽⁴⁾	44.7	0.1	4.0	0.6	8.3		38.7	3.2	0.2		2.0		2.0

⁽¹⁾ corrected from van Keken et al. (2011)

⁽²⁾ site dependent; see Table S2.

⁽³⁾ from Hacker (2008) with CO₂, H₂O, K₂O from Jarrard (2003)

⁽⁴⁾ DMM composition (Hacker, 2008) with 2.0 wt% H₂O added in top 2 km

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