

Nonlithostatic pressure during subduction and collision and the formation of (ultra)high-pressure rocks
Georg Reuber et al.

1 NON-LITHOSTATIC PRESSURES DURING SUBDUCTION

2 AND COLLISION – SUPPLEMENTARY MATERIAL

3

4 Here, we first describe the numerical method we use along with a discussion on the employed
5 rheologies and the use of plastic friction angle in many geodynamic models (part S1). In a
6 subsequent section (S2) we describe the model setup and compare results of our finite element
7 code with the earlier results of Li et al. (2010) obtained with a staggered finite difference
8 method. We than describe the effect of adding an inclusion in the reference model in more detail
9 (S3), followed by a summary of the systematic results (S4) and a discussion of the effect of
10 elasticity on the conclusions.

11

12 **S1. Method**

13 The simulations described in this paper are computed with the thermo-mechanical marker-and-
14 cell finite-element code, MVEP2 (Thielmann and Kaus, 2012; Johnson et al., 2014) that
15 simulates deformation of the lithosphere and mantle in the presence of a free surface for
16 temperature-dependent viscoelastoplastic rock rheologies.

17

18 ***Governing equations***

19 The conservation of mass and the momentum for slowly deforming incompressible rocks are

$$\frac{\partial v_i}{\partial x_i} = 0 \quad (1)$$

$$-\frac{\partial P}{\partial x_i} + \frac{\partial \tau_{ij}}{\partial x_j} = \rho g_i \quad (2)$$

20 where v_i denotes velocity, P pressure, τ_{ij} the components of the deviatoric stress tensor, g_i
 21 gravitational acceleration and ρ density. Density is assumed to be temperature-dependent
 22 according to:

$$\rho = \rho_0(1 - \alpha(T - T_0)) \quad (3)$$

23 where α is the thermal expansion coefficient, and ρ_0 the density at room temperature T_0 .

24 We employ a Maxwell visco-elasto-plastic rheology

$$\dot{\varepsilon}_{ij} = \dot{\varepsilon}_{ij}^{elastic} + \dot{\varepsilon}_{ij}^{viscous} + \dot{\varepsilon}_{ij}^{plastic} = \frac{1}{2G} \frac{D\tau_{ij}}{Dt} + \frac{\tau_{ij}}{2\eta_{eff}} + \lambda \frac{\partial Q}{\partial \sigma_{ij}} \quad (4)$$

25 where $\dot{\varepsilon}_{ij}$ are the components of the strain rate tensor, G the elastic shear modulus, $\frac{D\tau_{ij}}{Dt}$ Jaumann
 26 objective derivative of the deviatoric stress tensor (Thielmann et al., 2015), η_{eff} the effective
 27 viscosity which generally depends on stress and temperature, λ a plastic multiplier that ensures
 28 that stresses are below or at the yield stress, Q the plastic flow potential and $\sigma_{ij} = -P\delta_{ij} + \tau_{ij}$
 29 the components of the stress tensor with δ_{ij} being the Kronecker delta. **Most simulations**
 30 **presented here do not take elasticity into account for consistency with the earlier results of Li et**
 31 **al. (2010), which is achieved by setting G to a very large value (10^{60} Pa). Yet, we did test the**
 32 **effect of elasticity on our general conclusions which shows that it does not significantly change**
 33 **the results (section S5).** In addition, we also solve the energy equation which is given by

$$\rho c_p \left(\frac{\partial T}{\partial t} + v_i \frac{\partial T}{\partial x_i} \right) = \frac{\partial}{\partial x_i} \left(k \frac{\partial T}{\partial x_i} \right) + H_a + H_r + H_s \quad (5)$$

34 where c_p is the heat capacity, k the thermal conductivity, H_r radioactive heating, $H_s =$
 35 $\tau_{ij}(\dot{\varepsilon}_{ij} - \dot{\varepsilon}_{ij}^{elastic})$ shear heating caused by dissipative processes, and $H_a = -T\alpha\rho g_z v_z$ adiabatic
 36 heating.

37

38 ***Viscosity***

39 The effective viscosity is computed according to

$$\eta_{\text{eff}} = FA^{-1/n}(\dot{\varepsilon}_{II})^{\frac{1-n}{n}} \exp\left(\frac{E + PV}{nRT}\right) \quad (6)$$

40 where n is a powerlaw exponent, E the activation energy, V the activation volume, $\dot{\varepsilon}_{II} =$
 41 $(0.5\dot{\varepsilon}_{ij}\dot{\varepsilon}_{ij})^{0.5}$ the second invariant of the strain rate tensor, R the universal gas constant, F a
 42 coefficient that depends on whether the experiment was done for uniaxial or simple shear
 43 conditions (Gerya, 2009), and A an experimentally determined pre-factor. Values are taken from
 44 laboratory experiments and are listed in Table S2.

45 In all simulations in this paper, a viscosity cutoff of 10^{25} Pas and 10^{19} Pas is employed.

46

47 ***Plasticity***

48 The maximum stress of rocks is limited, and in the crust, this maximum yield stress is pressure
 49 dependent according to Byerlees law. The usual way in which this is modelled in geodynamic
 50 codes is by imposing a Mohr-Coulomb or Drucker-Prager yield criterium which is given by

$$\sigma_{yield} = C + \mu(P - P_f) \quad (7)$$

51 where C is the rock cohesion, P dynamic pressure, P_f fluid pressure and μ the coefficient of
 52 friction . Byerlees law, based on experiments, suggests that μ is 0.85 for pressures smaller than
 53 200 MPa and $\mu = 0.6$ for pressures larger than that (Byerlee, 1978). In-situ stress measurements
 54 in (deep) drill holes in the upper crust suggest that μ varies between 0.6 and 1.0 with the upper
 55 values being applicable for the uppermost crust (Townend and Zoback, 2000). The San Andreas
 56 Fault Observatory at Depth (SAFOD) drill-hole gave an opportunity to measure the plastic
 57 strength of rocks just outside and within the San Andreas Fault zone, which showed that μ is
 58 around 0.6 outside the fault and reduced to 0.15 on the actual fault itself (Lockner et al., 2011),

59 which suggests that Byerlees law is valid as a general first-order approximation of the yield
 60 stress of the overall crust, outside major fault zones which have smaller values. Often, the yield
 61 stress is expressed in terms of a friction angle rather than a friction coefficient, where $\mu =$
 62 $\tan(\phi)$. With that, equation (7) can be rewritten as

$$\sigma_{yield} = C + (P - P_f)\tan(\phi) \quad (8)$$

63 At yielding, the radius of the Mohr-circle touches the yield strength envelope. The radius of the
 64 Mohr circle is given by the second invariant of the (deviatoric) stress tensor, $\tau_{II} = (0.5\tau_{ij}\tau_{ij})^{0.5}$.
 65 This gives the following trigonometric expression

$$\sin(\phi) = \frac{\tau_{II}}{\frac{C}{\tan(\phi)} + (P - P_f)}$$

66 which can be written as

$$\tau_{II} = C\cos(\phi) + (P - P_f)\sin(\phi)$$

67 Stresses in the model should be smaller or equal to this yield stress

$$\tau_{II} \leq C\cos(\phi) + (P - P_f)\sin(\phi) \quad (9)$$

68 This can again be rewritten as

$$\tau_{II} \leq C\cos(\phi) + P\lambda\sin(\phi) \quad (10)$$

69 where $\lambda = \left(1 - \frac{P}{P_f}\right)$ is a factor that depends on how high the fluid pressure is. If there are no
 70 fluids, $P_f = 0$ and $\lambda = 1$. If, on the other hand, fluid is present in small unconnected pores within
 71 the rock, the fluid pressure might reach P and $\lambda = 0$. If fluid pressure is present in an
 72 interconnected network that reaches to the Earth surface, the fluid pressure is close to
 73 hydrostatic, and $P_f = \rho_f gz$, where ρ_f is the *fluid* density (around 1000 kg/m^3 for water) and z

74 the depth. If the rock pressure is lithostatic, $P = \rho g z$, which gives, using a rock density of 3000
75 kg/m^3 , $\lambda = \frac{2}{3} = 0.67$. If, however, rock pressure is twice larger than lithostatic and fluid pressure
76 remains hydrostatic we obtain $\lambda = \frac{5}{6} = 0.83$.

77 Some authors use an *effective* friction angle ϕ_{eff} rather than the true friction angle ϕ and a pore-
78 fluid factor λ . This can be derived by stating that

79
$$\sin(\phi_{\text{eff}}) = \lambda \sin(\phi)$$

80 in that case we can reformulate equation (10) as

$$\tau_{II} \leq C \cos(\phi) + P \sin(\phi_{\text{eff}}) \quad (11)$$

81 With $\phi_{\text{eff}} = \arcsin(\lambda \sin(\phi))$. This derivation shows that even if we use an effective friction angle
82 in the yield stress, we also need to take the “dry” friction angle ϕ into account. Some authors
83 simply replace the friction angle in their model ϕ_{eff} with a smaller value ϕ_{eff} and justify this
84 with elevated fluid pressures. The yield stress criterion they solve in that case is:

85
$$\tau_{II} \leq C \cos(\phi_{\text{eff}}) + P \sin(\phi_{\text{eff}})$$

86 which is only correct if the cohesion is zero (which it often is not). Whereas it might be argued
87 that cohesion is a small term in the expression above, this discussion does show that it is actually
88 better to incorporate equation (10) directly in the numerical code rather than using small friction
89 angle values.

90 As discussed, experimental evidence in rocks from the SAFOD experiment shows that $\mu =$
91 0.6 ($\phi = 31^\circ$) in the crust (also just outside the large fault zone), and is only reduced to smaller
92 values of $\mu = 0.15$ ($\phi = 8.5^\circ$) within the actively deforming fault zones. If one wishes to
93 correctly model the long-term averaged state of stress in the crust, it is thus probably best to use
94 a “dry” coefficient of friction for crustal rocks, and weaken this within fault zones only.

95 Models of subduction dynamics and collision generally use a rather small friction angle within
96 the subduction channel to prevent unrealistically high topographies and slab breakoff to develop,
97 an effect which we also find in our simulations. Using a low friction angle for sedimentary rocks
98 at the ocean floor seems indeed justified to a certain extent as (unconsolidated) sediments on the
99 ocean floor are water rich and might develop high fluid pressures at larger depth.

100 Another recent argument is that melt propagation in dikes results in short bursts of weakness of
101 the lithosphere. The long-term mechanical behavior of the lithosphere, and the dissipation of its
102 mechanical energy, was shown to strongly correlate to the energy that is dissipated during rapid
103 magmatic dike events, which was shown to result in values of λ of 10^{-4} - 10^{-2} (Gerya et al.,
104 2015). Whereas we agree that the mechanical deformation of the lithosphere might be controlled
105 by the small period's weakness, using very small values of λ will result in small stresses (and
106 pressures) throughout the whole simulation. Metamorphic reactions require time and as such
107 they are more likely controlled by the larger stresses that exist during amagmatic periods, rather
108 than by what happens during a rapid magmatic event, and we would therefore argue for using the
109 dry friction values throughout most of the crust and employing small values only on strongly
110 weakened fault zones.

111 From the yield stress expression (eq. (10)), one can compute an effective plastic viscosity:

$$\eta_{pl} = \frac{C\cos(\phi) + P\lambda\sin(\phi)}{2\dot{\varepsilon}_{II}} \quad (12)$$

112 The effective plastic viscosity is then adapted such that stresses remain at or below yield stresses,
113 which require nonlinear iterations (Kaus, 2010). In our code we employ fixed-point iterations to
114 deal with those.

115 ***Erosion and sedimentation***

116 The free surface h_{topo} evolves according to:

117

$$\frac{\partial h_{\text{topo}}}{\partial t} + v_x \frac{\partial h_{\text{topo}}}{\partial x} + v_z \frac{\partial h_{\text{topo}}}{\partial z} = v_s + v_{er}$$

118 where v_s is the sedimentation rate which is 1 mm/yr if $h_{\text{topo}} < 100\text{m}$, and v_e
 119 is the erosion rate which is -3 mm/yr if $h_{\text{topo}} > 4000\text{m}$. The free surface is remeshed to the
 120 new grid location at every time step, using the x-coordinates of the finite element mesh.

121

122 ***Numerical method***

123 Our numerical equations (1-6) and (11) are solved numerically using the MATLAB-based finite
 124 element method MVEP2, which is a further-development of MILAMIN_VEP (Kaus, 2010;
 125 Thielmann and Kaus, 2012) that uses markers to track material properties, and creates a new
 126 topography-following mesh at every time step. As most other geodynamic codes, we use
 127 pressure, velocity and temperature as primary variables. For most simulations reported here, we
 128 employ Q₁P₀ elements with direct solvers. We performed a few tests with higher order Q₂P₋₁
 129 elements and found the first-order effects such as geometry, magnitude and distribution of
 130 pressures to be the same, even though the peak pressures are slightly larger for Q₂P₋₁ elements
 131 (on the order of ~100 MPa in the strong inclusion case of Figure 1).

132

133 ***Non-lithostatic pressure***

134 Pressure is defined as the negative trace of the stress tensor and is one of our solution variables,
 135 and since we use a free surface upper boundary condition it is uniquely defined in our
 136 simulations. In order to compare this with the lithostatic pressure we need a method to compute
 137 the equivalent lithostatic pressure everywhere in our model. Technically, it can be derived from
 138 the force balance equation (eq. (2)) under the assumption that deviatoric stresses are zero, which
 139 gives:

$$-\frac{\partial P_L}{\partial z} = \rho g \quad (13)$$

140 In the case that density is constant and gravity acts in the negative vertical direction and is zero at
 141 the Earth's surface, we can solve this analytically:

142 $P_L = \rho gh$

143 where h is depth. Yet, in our models density actually depends on phase and temperature.
 144 Moreover, we use a deformed finite element mesh where density values are only evaluated at
 145 integration points. In order to compute lithostatic pressure in that case, we could interpolate
 146 density values on a regular grid and integrate the pressure numerically, starting at the surface.
 147 Yet, this gives rise to interpolation errors. A better method is to discretize equation (13) with a
 148 finite element method and employ the same shape functions and deformed elements as we use in
 149 the thermomechanical code. This requires a boundary condition, which is that $P_L = 0$ at the
 150 surface. We implemented this method which compares well with the normal integration method
 151 but is more consistent with the overall code. Once this is computed, the non-lithostatic pressure
 152 can be evaluated with

$$P_T = P - P_L \quad (14)$$

153 ***Tracking P-T evolution of rocks***

154 In order to create plots of the maximum pressure that a particle experienced during its model
 155 evolution, one could store all particles during the full model evolution. Yet, in practice this
 156 requires immense storage volumes, particularly if several hundred simulations are performed.
 157 We therefore use a different technique, which traces particles backwards in time though the
 158 model using a 4th order Runge-Kutta method in time, which uses stored velocity fields. We
 159 compared this method with simulations in which the full particle fields were stored and found
 160 that this method yielded nearly identical results provided that sufficient intermediate velocity

161 fields are stored. We used this method to create plots of the maximum pressure that a marker
162 experienced during its model evolution in figure 1.

163 The PT-paths shown in figure 1 were computed from a single marker, but we compared the
164 results with a case in which 50 markers were used and found the results to be similar.

165 The quartz/coesite phase transition was calculated using THERMOCALC v3.62 and the Holland &
166 Powell (2011) database.

167

168 ***Rheology parameters employed***

169 A summary of all rheology parameters employed in the models is given in Table S1. Parameters
170 are taken from (Shelton and Tullis, 1981; Kirby, 1983; Ranalli and Murphy, 1987; Wilks and
171 Carter, 1990; Bittner and Schmeling, 1995; Ranalli, 1995; Mackwell and Zimmerman, 1998;
172 Turcotte and Schubert, 2002).

173

174 **S2. Model setup and reproducing earlier results**

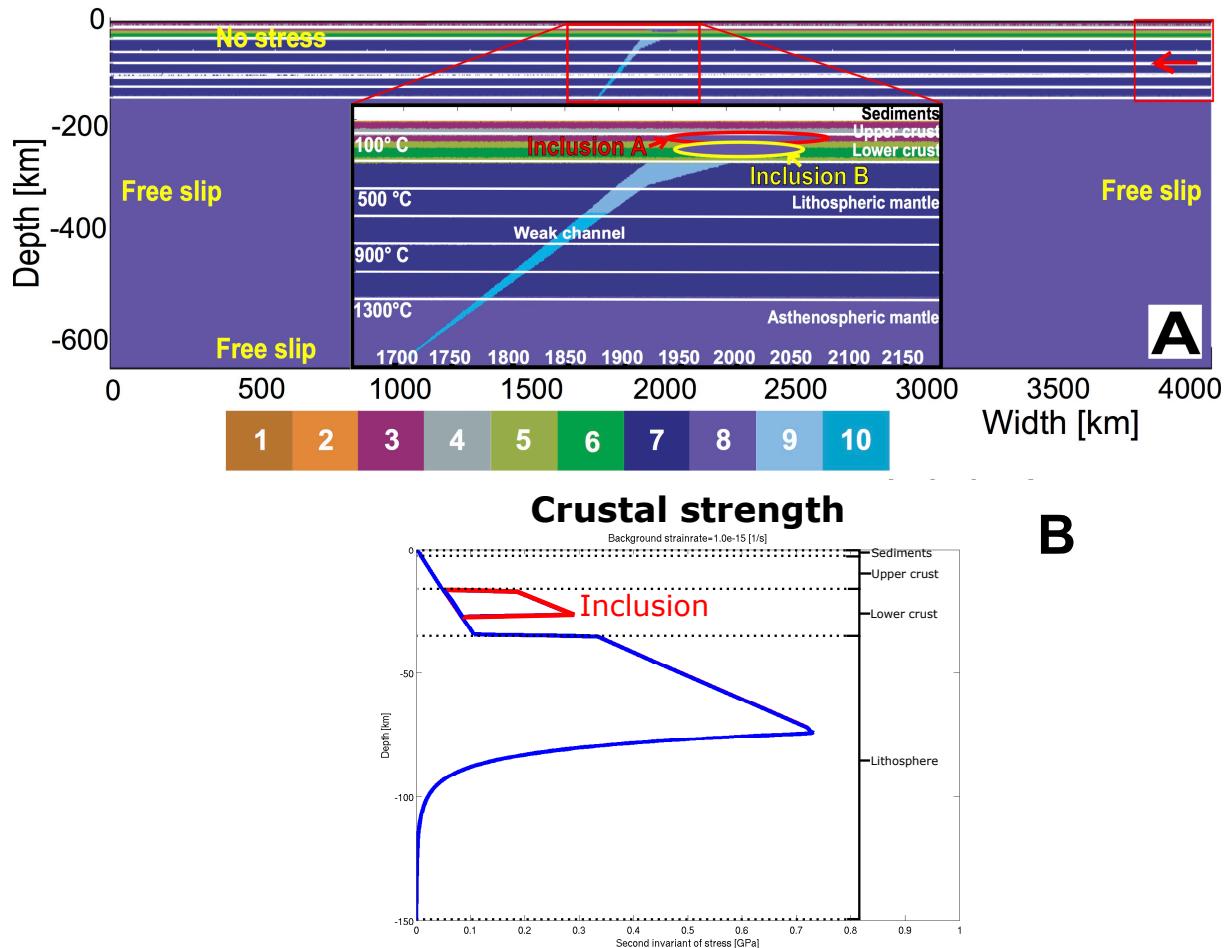
175 ***Model setup***

176 Unlike the study of Li et al. (2010), which employed a marker and cell finite difference method
177 (Gerya and Yuen, 2007), we use an independently developed thermo-mechanical finite element
178 code (MVEP2; see supplementary material and (Thielmann and Kaus, 2012; Johnson et al.,
179 2014) for details). The initial model setup has two continents, each with a 2 km sedimentary
180 cover layer, a 15.5 km thick quartzitic upper and a 17.5 km thick plagioclase lower crust (Figure
181 S1a; see table S1 for all employed model parameters). Subduction is initiated by imposing a
182 constant convergence velocity of 3 cm/a for the rightmost lithosphere together with an initial
183 weak zone. The initial geotherm increases linearly from 0°C at the surface to 1350°C at 150 km

184 depth (i.e., 9°C/km), after which it increases adiabatically to 1605°C at the isothermal lower
185 boundary. The side and lower boundaries are free slip whereas the upper boundary is stress free,
186 which is slightly different than the models of (Li et al., 2010) who use an “infinite-like” lower
187 boundary together with a sticky air layer to simulate water and air (see Fig. S1a for the model
188 setup). The upper boundary is subjected to a constant erosion rate of 3 mm/a when the elevation
189 is higher than 4 km and to a constant sedimentation rate of 1 mm/a for areas below 100 meters
190 (Li et al. 2010 did not specify an erosion/sedimentation rate but from their figures it appears that
191 erosion was active). We employ \sim 7 million markers to track composition and temperature and
192 employ quadrilateral finite elements with a resolution that varies from 30x30 km at the lateral
193 boundaries to 2x2 km around the subduction zone. The rheology we employ uses laboratory-
194 derived creep laws for viscous rocks combined with a frictional plastic (pressure-dependent)
195 yield stress (see Fig. S1b for a strength-envelop representation of the rheology used in our
196 models, for a constant background strain rate of 10^{-15} s^{-1}). Our model parameters closely follow
197 those used by (Li et al., 2010) (see supplementary tables 1), but are not identical. We, for
198 example, use a constant rather than a temperature dependent thermal conductivity and ignore
199 melting and crystallization.

200 The reference simulation has a laterally homogeneous crust with a plastic friction angle of 7° , to
201 reflect high fluid pressures in the crust. This value is considerably smaller than the $\sim 40^{\circ}$
202 determined experimentally (Byerlee, 1978) and $\sim 30^{\circ}$ by in-situ stress measurements in boreholes
203 (Townend and Zoback, 2000).

204
205



206
207 **Figure S1 | Model setup and strength for the simulations shown here:** A) The model setup consists of two
208 continents separated by a weak zone, where colors indicate: ^{1,2}Sediments; ^{3,4}Upper crust; ^{5,6}Lower crust;
209 ⁷Lithospheric mantle; ⁸Asthenospheric mantle; ⁹Upper weak zone; ¹⁰Lower weak zone. The lithosphere is pushed
210 from the right with a constant velocity within the red box. B) Strength envelop for the model setup we employed
211 under a constant, pure shear, background strain rate of 10^{-15} s^{-1} (note that strain rates, and therefore stresses, in the
212 2D simulations vary significantly).

213

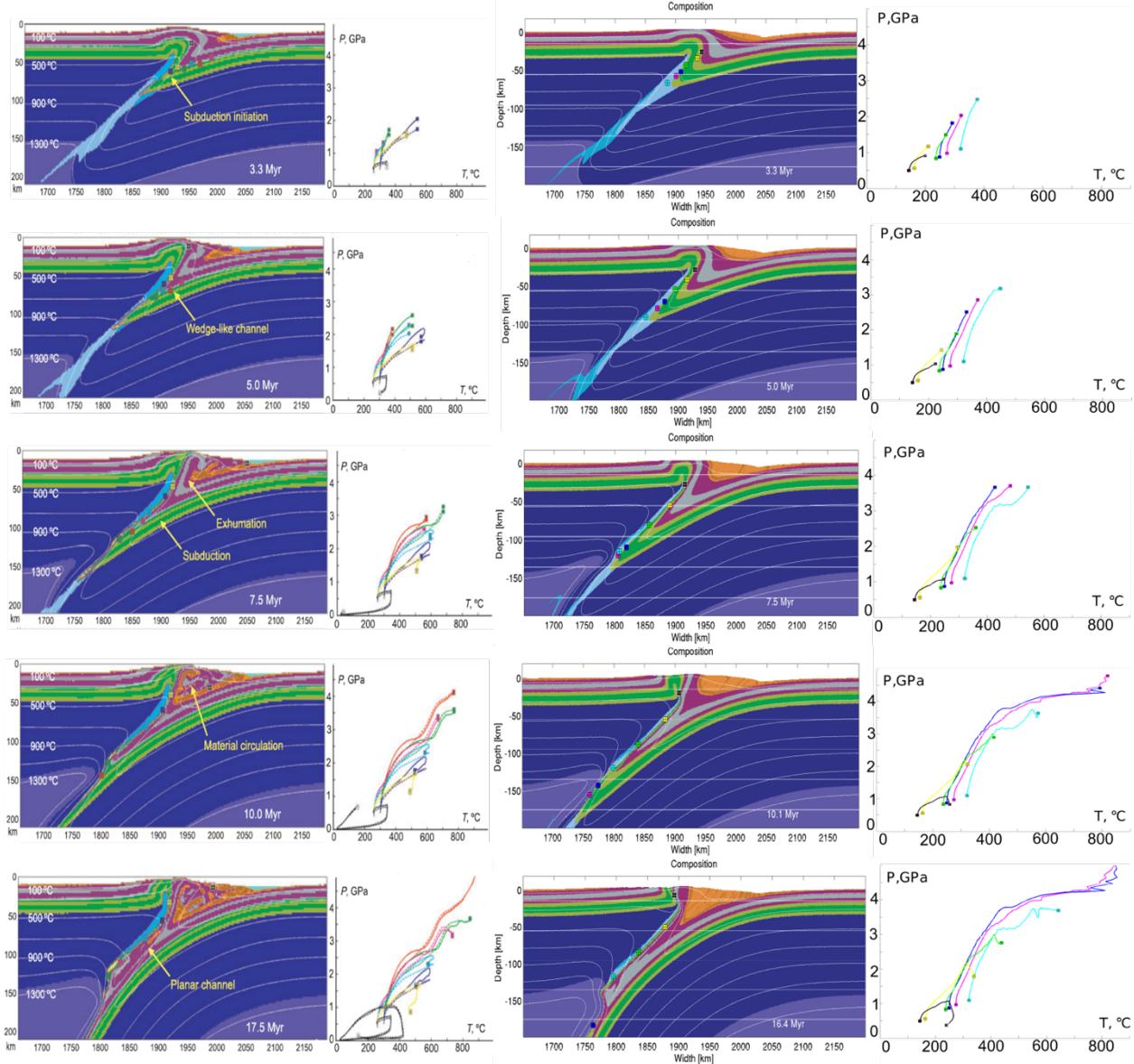
214 ***Reproducing earlier results***

215 The simulation results in subduction initiation, followed by formation of a subduction channel,
216 burial and exhumation of upper crustal rocks and subduction of lower crustal rocks. The overall

217 geometry and thermal evolution of our model is very similar to the previously published results,
218 apart from small-scale features within the upper crust and subduction wedge (Figure S2). Plots of
219 the non-lithostatic pressure component during various model stages are similar as well, and show
220 that pressures within the strong mantle lithosphere can strongly deviate from lithostatic
221 (supplementary Figure S3 and S4). In both models, pressures within the subduction channel,
222 from which rocks are exhumed at later stages, remain close to lithostatic suggesting that
223 petrological pressure estimates can be directly transferred into depth for low effective friction
224 angles.

225 Overall, the results agree, but there are some differences in the numerical approach. First, we
226 used a free slip lower boundary condition, rather than an ‘infinite’ like lower boundary, which
227 might be the major reason why Li et al. (2010) have a change in slab polarity in the middle of the
228 simulation, which our results do not show. Also, it was not possible to obtain the exact same
229 number of particles or the geometry of the subduction channel. We did not implement the phase
230 transition to molten material and do not set a ‘water’ phase if topography is below zero, which
231 might be the reason for the different material circulation within the sediment phase. Given that
232 we use completely independently developed codes and even different numerical techniques, we
233 can reproduce their results reasonably well particularly with respect to the shape of the
234 subduction channel and the maximum non-lithostatic pressure values reached. Differences in the
235 deformation patterns in the crust are expected as such fine scale features are not resolved with
236 the model resolution employed here.

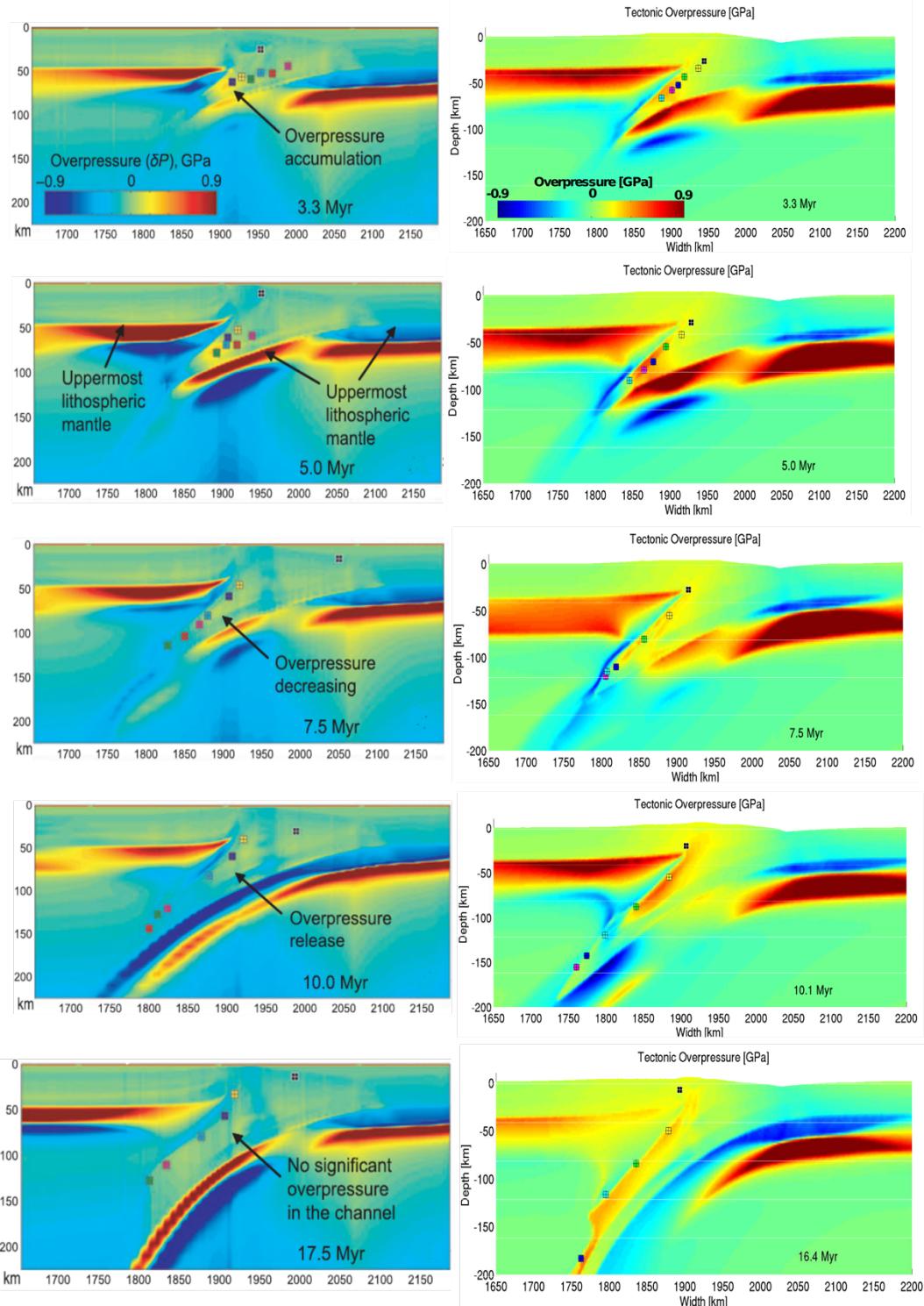
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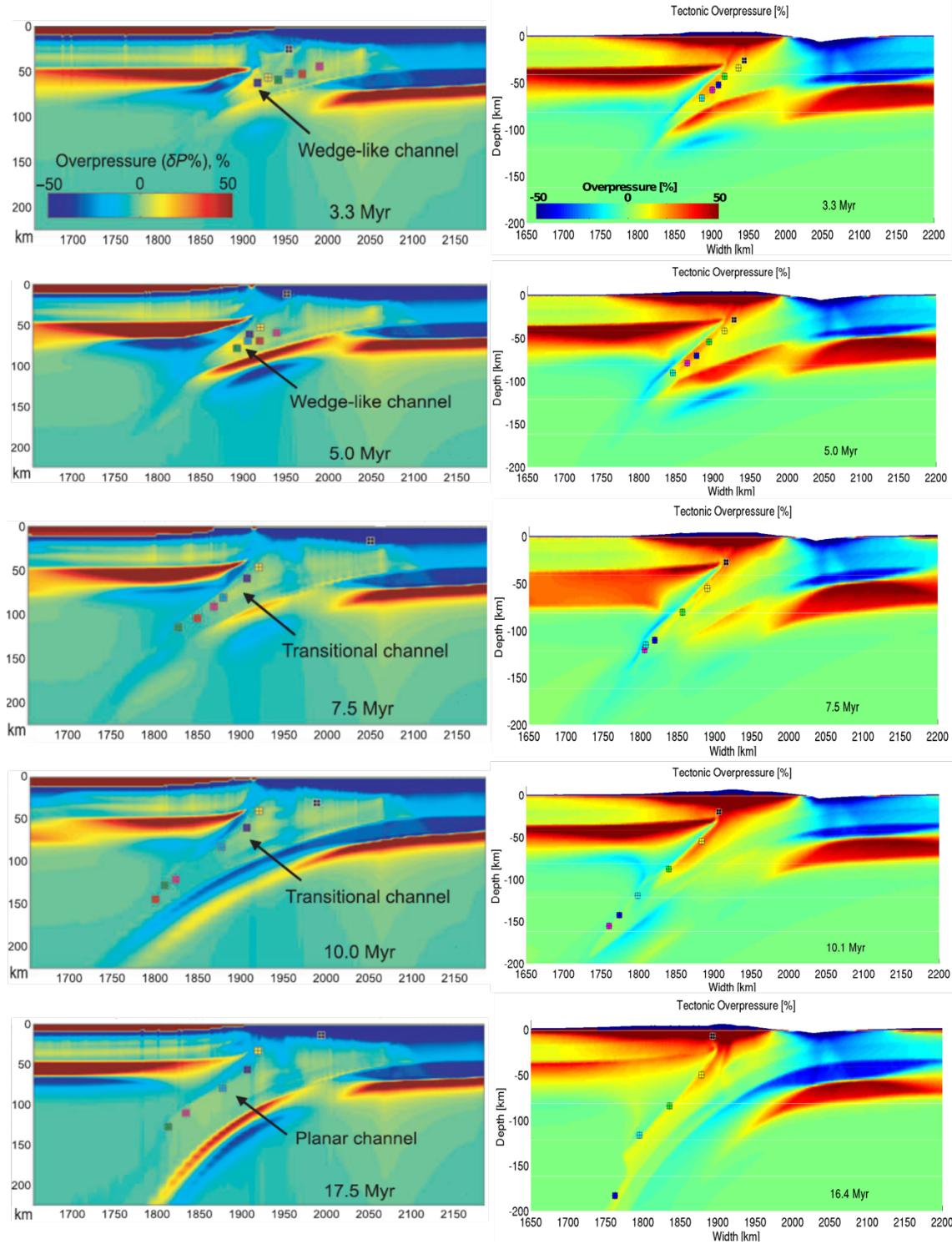
239 **Figure S2 | Comparison of I2VIS vs MVEP2.** Left column: Original pictures by Li et al. (2010) showing the
 240 evolution of their reference model. The P-T paths show the pressure-temperature history of the highlighted markers.
 241 Right column: Our reproduction of their reference model, using a different numerical code (MVEP2), and slightly
 242 different lower boundary conditions (free slip rather than an infinitely-like boundary condition). The markers for the
 243 P-T paths have slightly different locations than the ones in Li et al. (2010).

244



245

246 **Figure S3. Non-lithostatic pressure, I2VIS vs. MVEP2.** Left column: Original pictures taken from Li et al. (2010)
 247 showing the non-lithostatic pressure in GPa. Right column: Our reproduction of the non-lithostatic pressure in their
 248 reference model also in GPa.



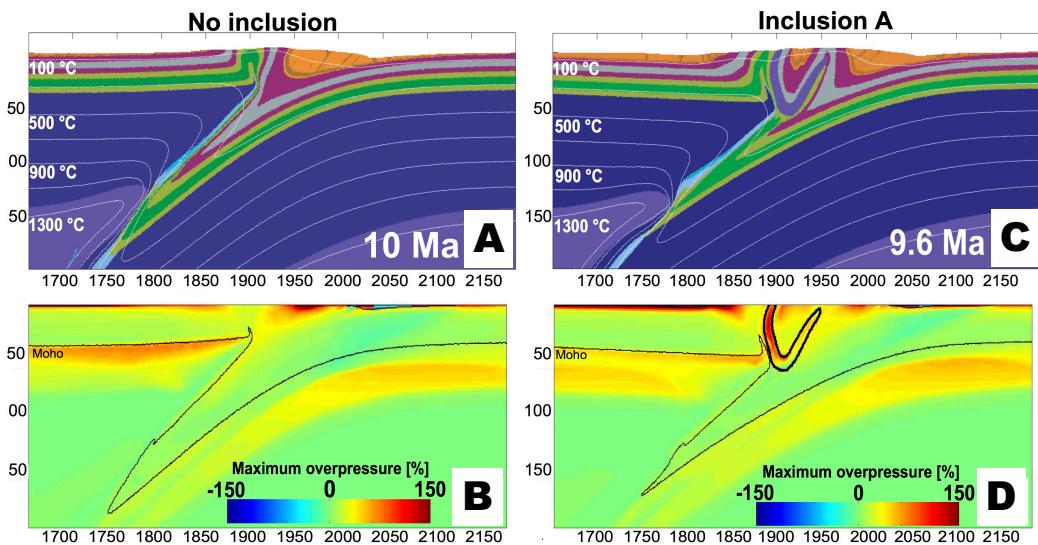
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250 **Figure S4. Relative non-lithostatic pressure, I2VIS vs. MVEP2.** Left column: Original pictures taken from Li et
 251 al. (2010) showing the non-lithostatic pressure as percentage of the lithostatic pressure. Right column: Our
 252 reproduction of the non-lithostatic pressure in their reference model also as percentage of the lithostatic pressure

253 **S3. Effect of heterogeneity**

254 In order to test the effect of heterogeneities, we emplaced a heterogeneity of type "A" (Fig. S1)
255 at the upper/lower crust boundary which is otherwise identical to the one described earlier. The
256 heterogeneity has a thickness of 10 km and a width of 150 km, which is larger than typical
257 crustal heterogeneities but ensures that it is computationally well-resolved. Results show that the
258 presence of the heterogeneity affects the deformation and exhumation patterns within the upper
259 crust and mountain belt, but does not have a major impact on the overall subduction dynamics
260 (Figure S5a). Yet, the maximum recorded pressures during the lifetime of the heterogeneity are
261 significantly larger than lithostatic (Figure S5b), which can be attributed to compression and
262 bending of the layer.

263

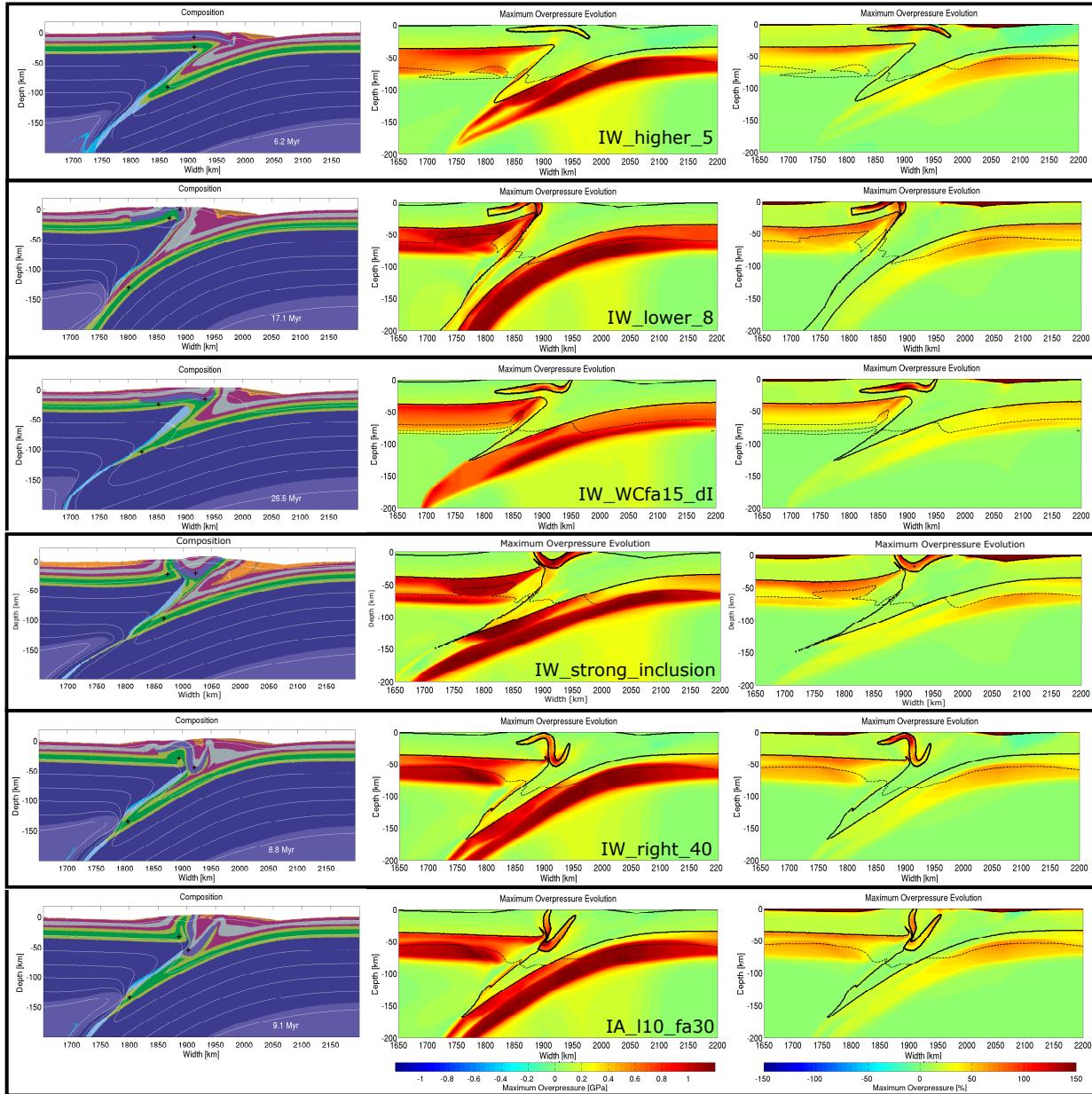


264

265 **Figure S5 | Simulations with homogeneous and heterogeneous crust:** A) Model evolution of a simulation with a
266 homogeneous and weak crust, with an effective friction angle of 7° (as in Li et al. (2010)). B) The maximum non-
267 lithostatic pressure that every marker experienced during the full model evolution after 10 Ma, normalized to the
268 lithostatic pressure, which shows that the subduction channel is close to lithostatic in agreement with earlier results.
269 C) Simulation in which a strong inclusion was inserted in the otherwise weak crust (inclusion A) and E)
270 corresponding non-lithostatic pressure, which demonstrates that the exhumed heterogeneity has experienced
271 significant non-lithostatic pressures.

272 **S4. Overview of systematic simulations**

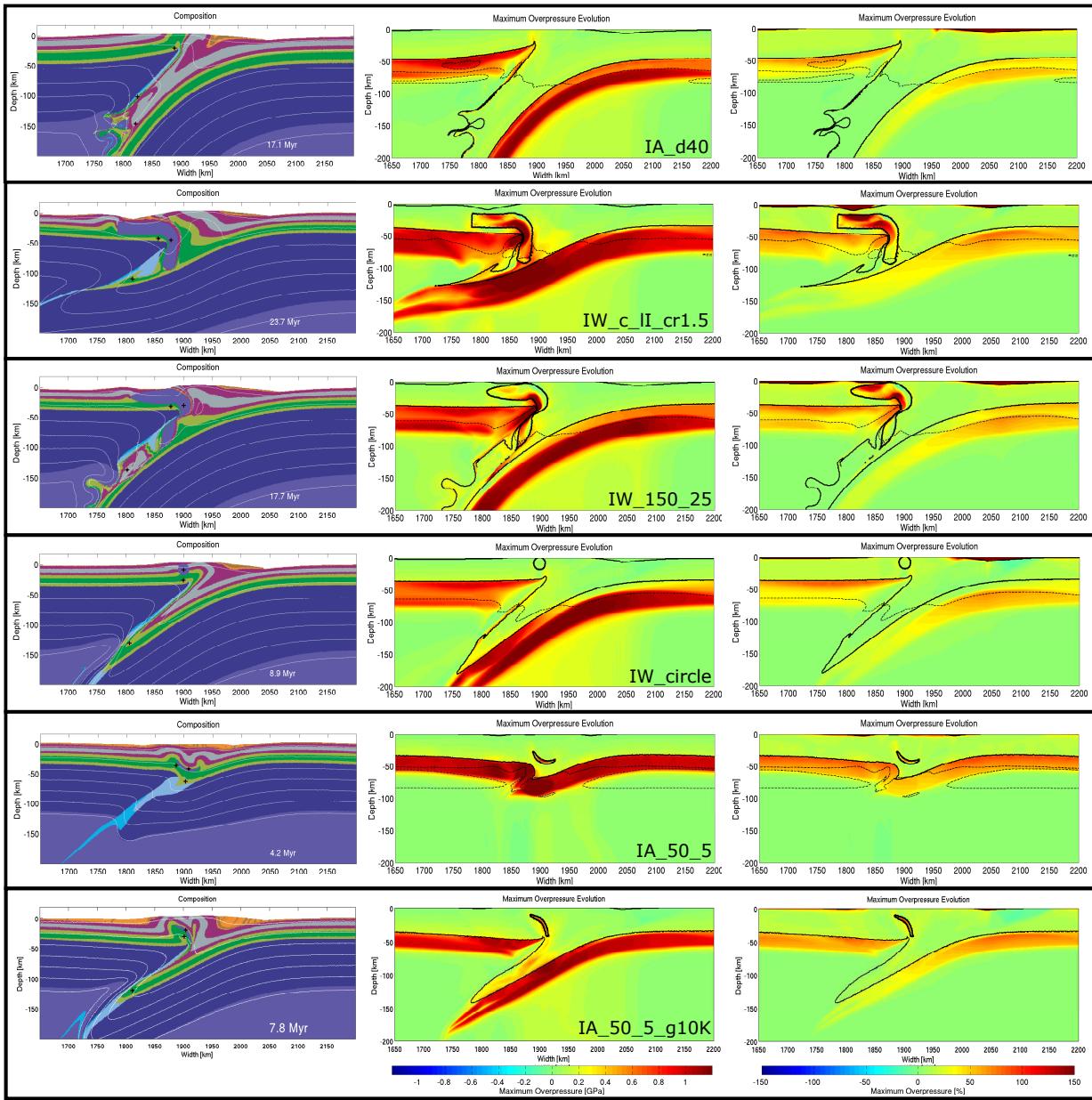
273 We have performed in total over 400 simulations, of which we compiled about 130 simulations
 274 in Table S2 as they are closely related to the model setup in the main paper. Simulations shown
 275 in figure 1 and 2 are highlighted in red, and simulations shown on Fig.S6 in green in the table.



276

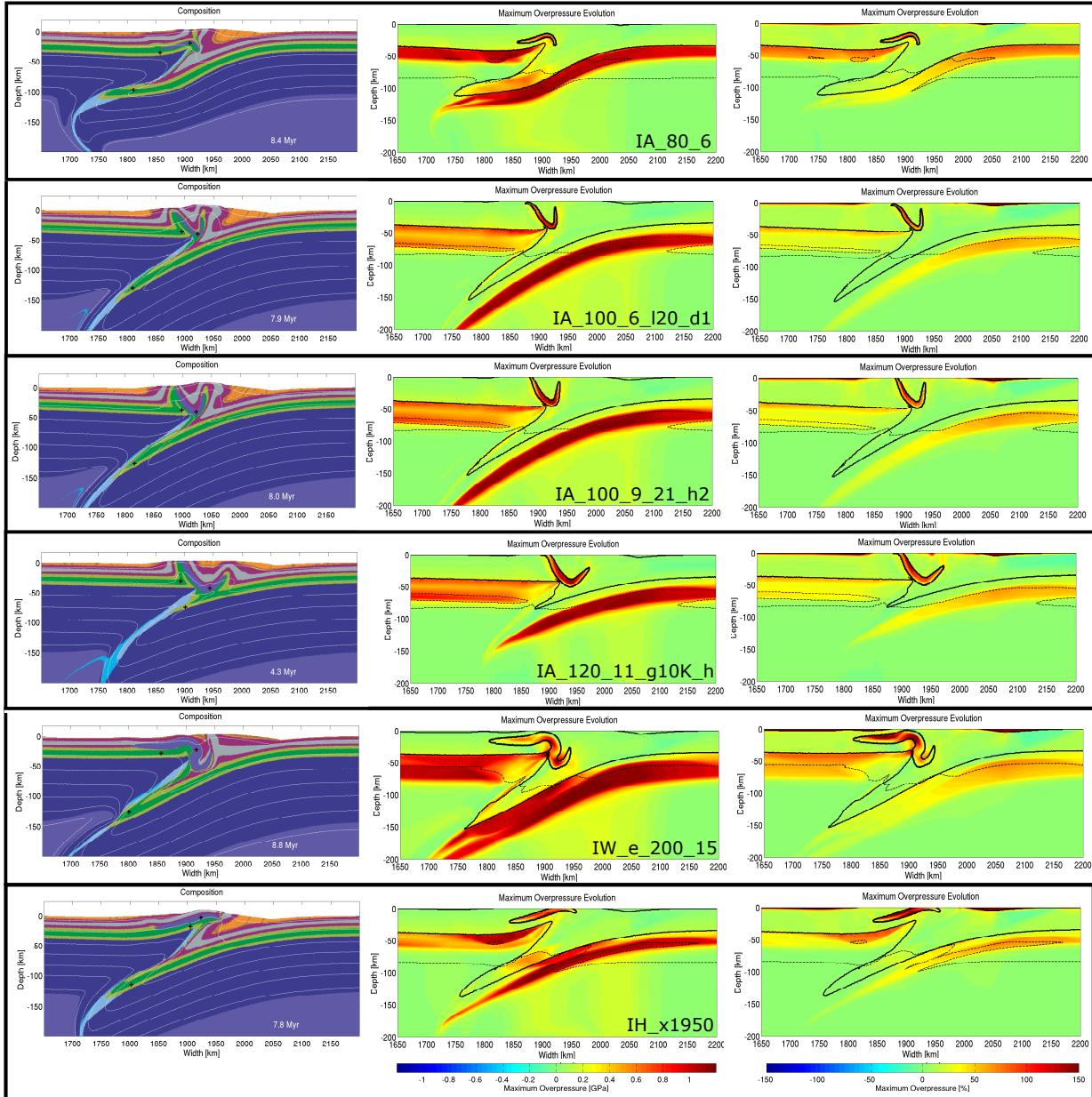
277 **Figure S6, Part 1 | Systematic simulations.** For each simulation, the geometry at the end of the simulation is
 278 shown (left), and the maximum overpressure particles experienced both in absolute and relative terms. Crosses
 279 indicate traced points that are used for the compilation of figure 2 (note that in figure only cases with a strong lower
 280 crust were included, but that all inclusion and weak subduction channel tracers are shown). Names in the middle
 281 column refer to Table S2.

282



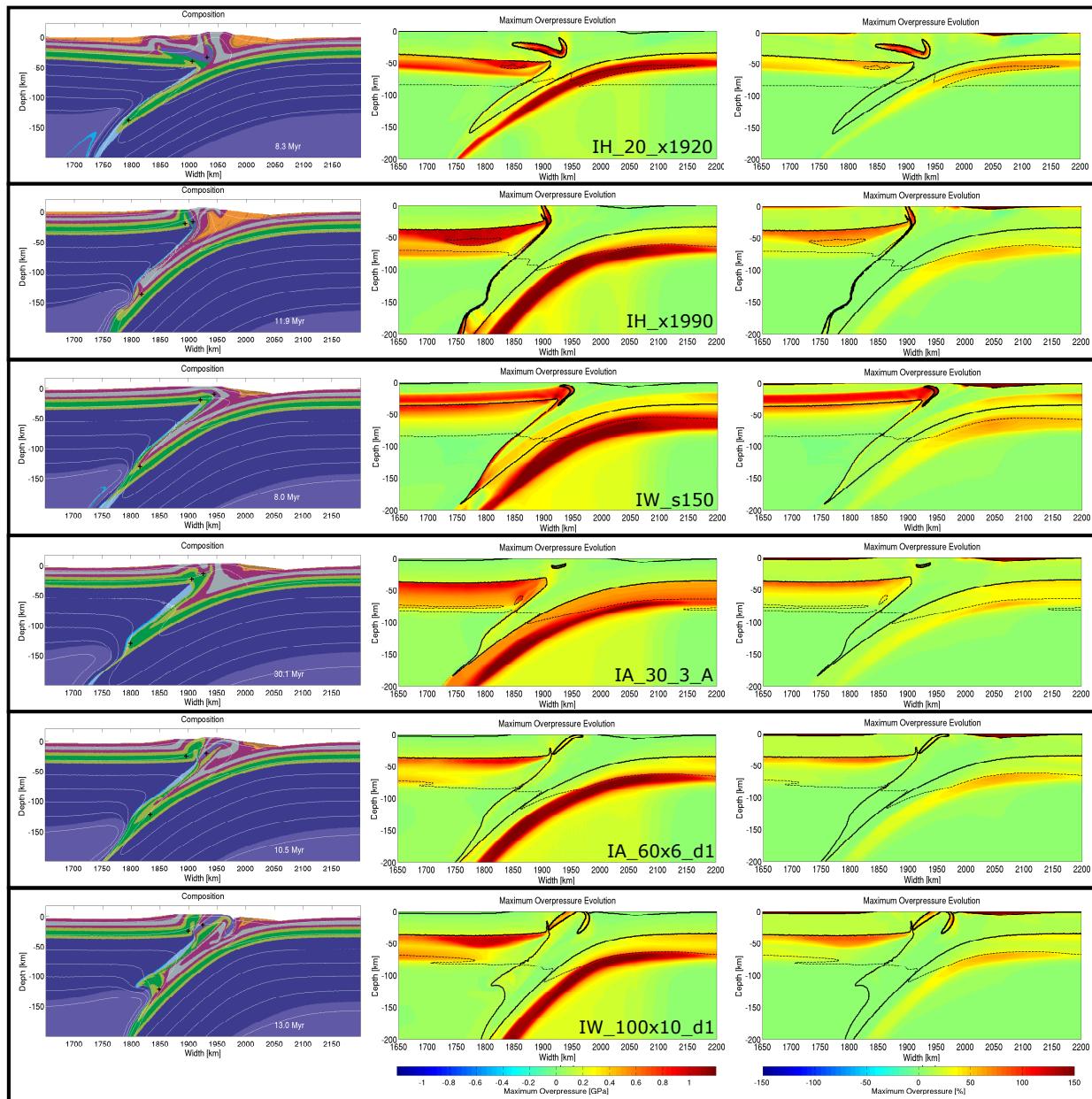
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284 **Figure S6, Part 2 | Systematic simulations.**



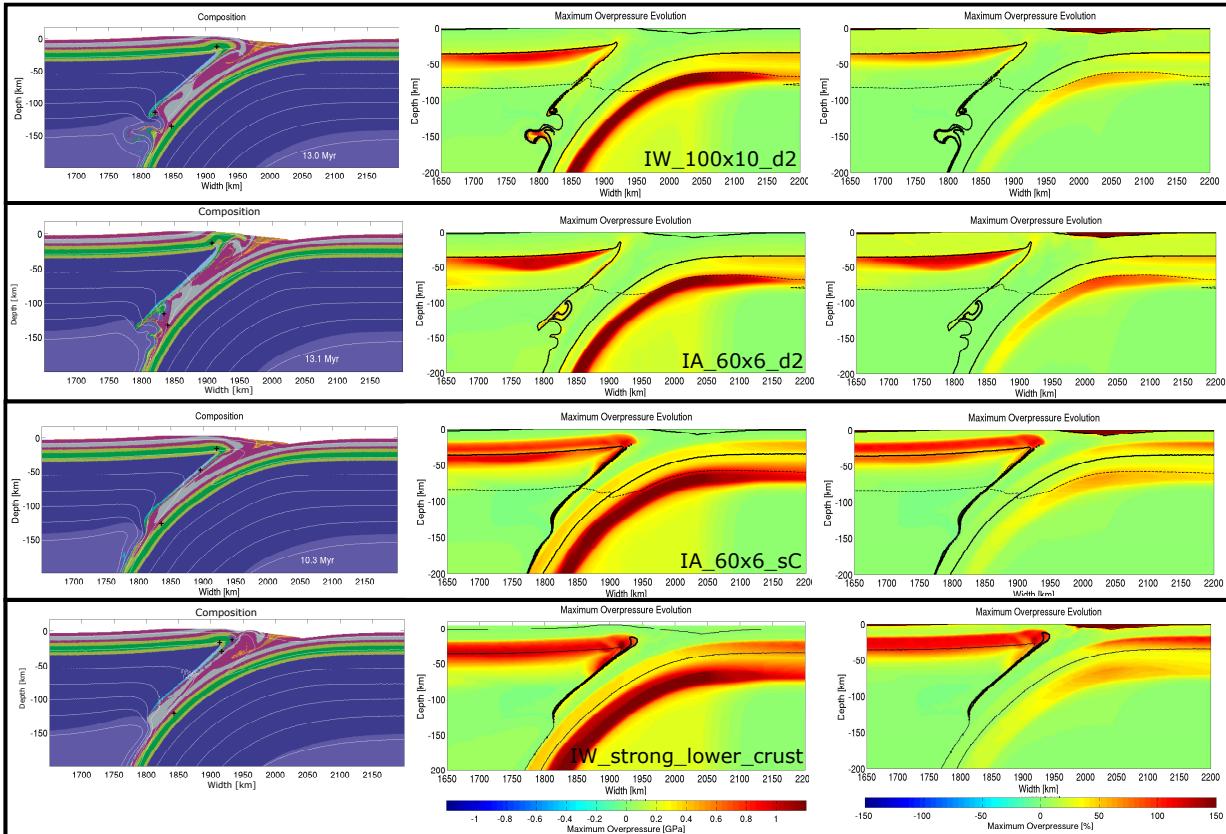
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286 **Figure S6, Part 3 | Systematic simulations.**



287

288 **Figure S6, Part 4 | Systematic simulations.**



289

290 **Figure S6, Part 5 | Systematic simulations.**

291

292 The PT evolution of the tracers are shown on figure S7, whereas the temporal evolution of
 293 pressure and temperature is shown on figure S8.

294

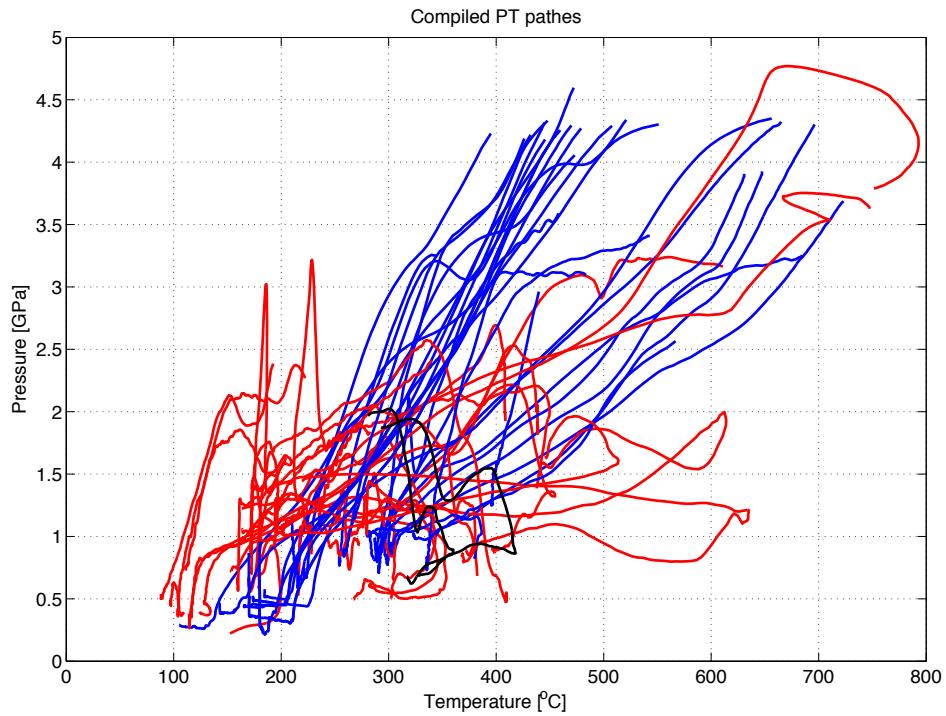


Figure S7. PT-path of the systematic simulations shown in Fig 2. Red lines refer to inclusions, blue lines to tracers within the subduction channel and black lines to tracers within the strong lower crust.

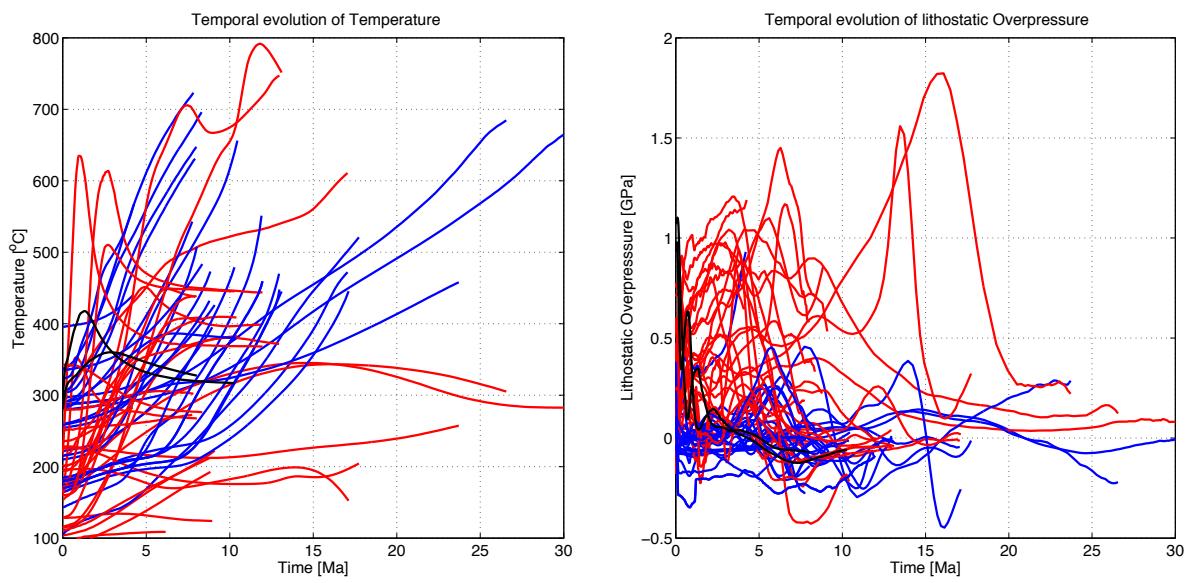


Figure S8. Temporal evolution of temperature and pressure of tracers. Strong fluctuations in the temperature curves are caused by a shear heating instability event, whereas a more gradual increase is caused by ordinary warming within a subduction channel. Fluctuations in pressure occur as a result of deformation of the inclusion and the evolution of the whole collision system.

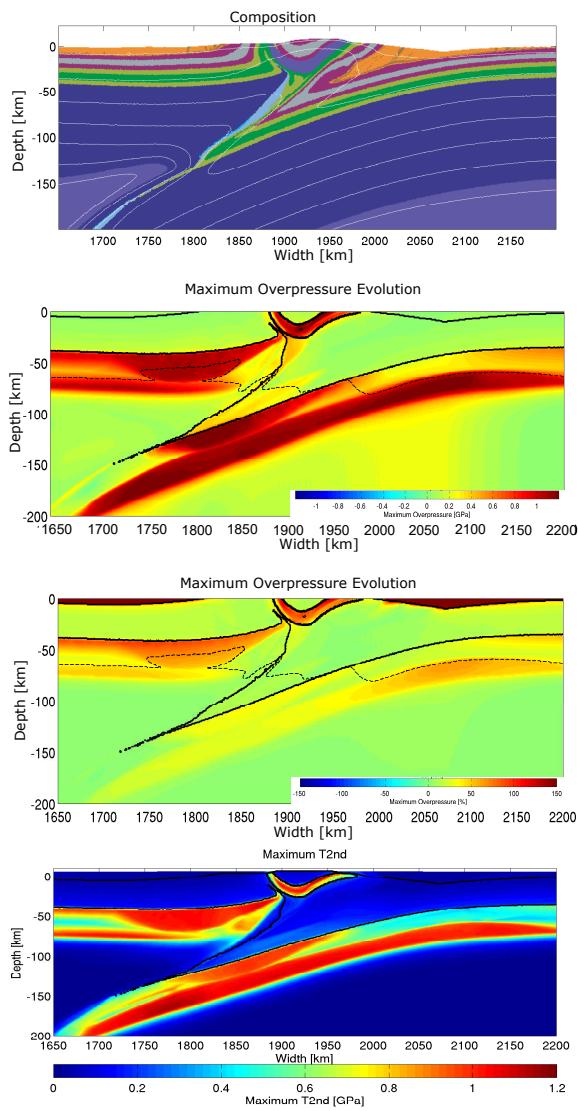
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305 **S5. Effect of elasticity**

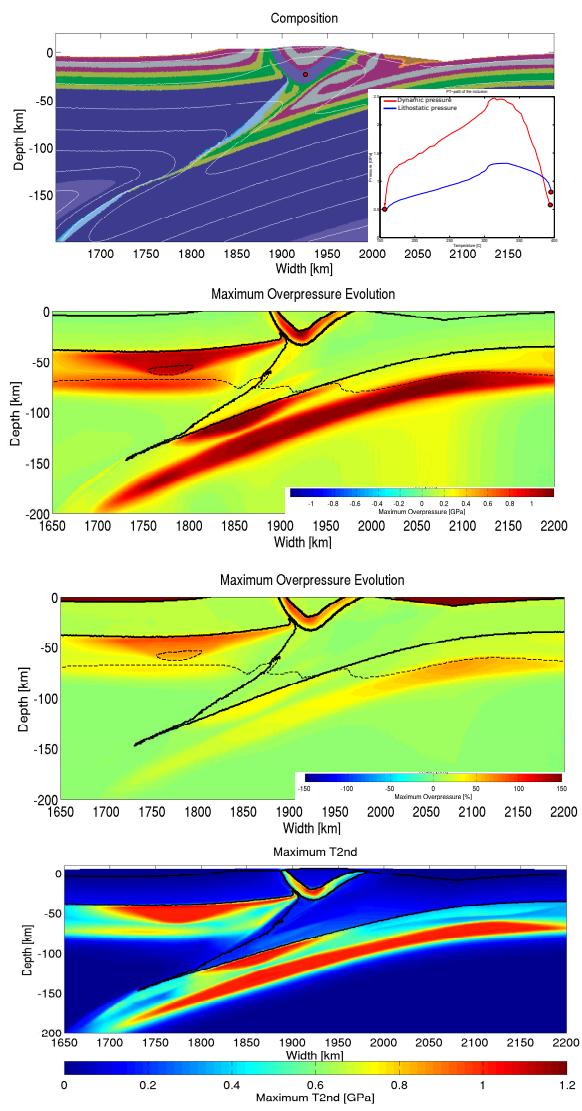
306 For consistency with the earlier results of Li et al. (2010) we performed most simulations with a
307 viscoplastic rheology. Yet, real rocks have elastic effects as well and it is thus interesting to see
308 whether the effects of elasticity significantly alter the results described here. We have therefore
309 repeated the simulations shown on Fig. 1 with elasticity included (using an elastic shear module
310 of $G=10^{11}$ Pa), starting from an initially stress-free state. Results show that the overall
311 subduction geometry is largely the same, as is the shape of the heterogeneity (Fig. S9 and S10).
312 The distribution of the overpressure areas is similar, even though peak pressures are slightly
313 lower (in the strong inclusion case, we obtain a peak pressure of ~2.5 GPa, vs 2.6 GPa in the
314 viscoplastic case). Some differences exist in the distribution of the deviatoric stresses, which we
315 attribute to the fact that deformation was ongoing during the stress-buildup stage of our
316 simulations. In nature, it is unlikely that continental collision starts from an initially stress-free
317 state, which would likely reduce the differences between the two endmember cases.

Strong inclusion

viscoplastic



viscoelastoplastic



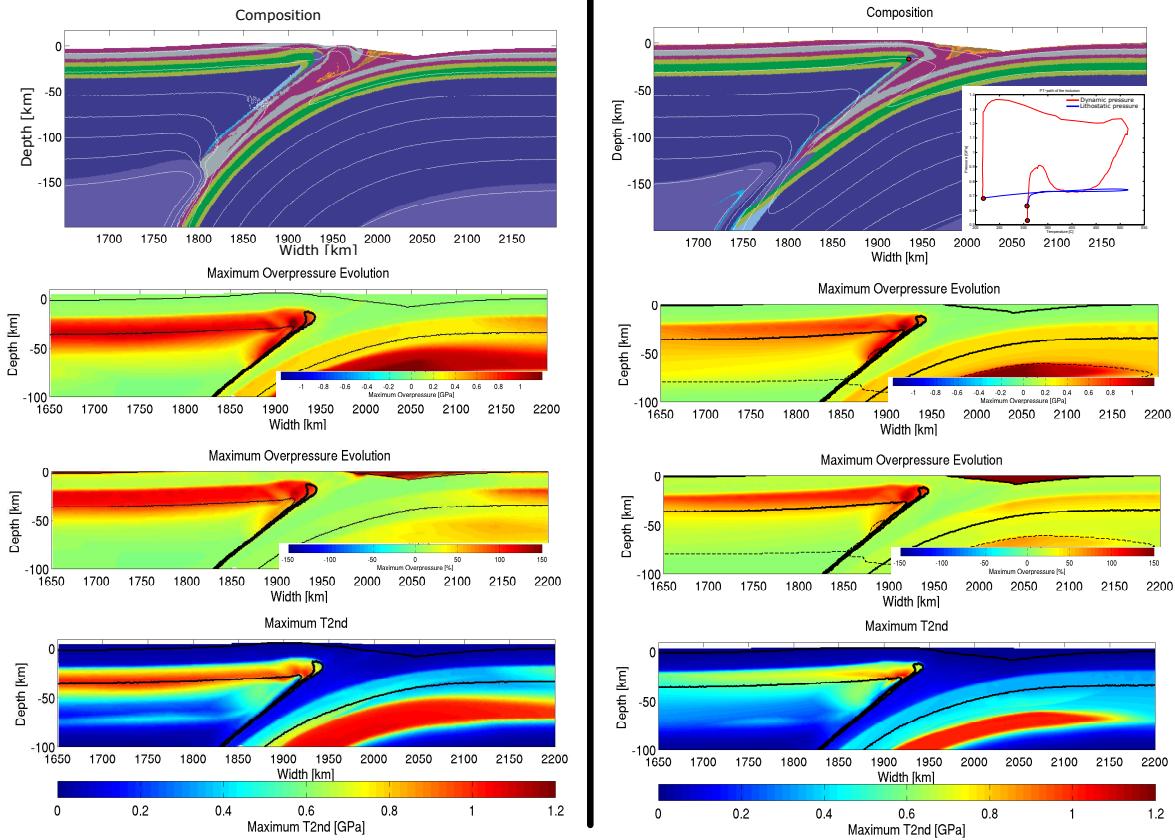
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Figure S9. Viscoplastic vs. viscoelastoplastic simulations for the case with a strong heterogeneity. Left: the simulation shown on Figure 1a which has a viscoplastic rheology after 10.4 Ma. Right: the same simulation but with a viscoelastoplastic rheology after 10.0 Ma. Shown are the geometry, relative and absolute overpressure obtained throughout the simulation and the maximum of the second invariant of the deviatoric stress tensor achieved during the simulation. Inset shows a typical P-T path.

Strong lower crust

viscoplastic viscoelastoplastic



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326 **Figure S10. Viscoplastic vs. viscoelastoplastic simulations for the case with a strong lower crust.** Left: the
327 simulation shown on Figure 1b which has a viscoplastic rheology after 8.1 Ma. Right: the same simulation but with
328 a viscoelastoplastic rheology after 8.0 Ma. Shown are the geometry, relative and absolute overpressure obtained
329 throughout the simulation and the maximum of the second invariant of the deviatoric stress tensor achieved during
330 the simulation. Inset shows a typical P-T path.
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Phase	c_p [J/K]	k [W/(mK)]	Q [W/m ³]	ρ_0 [kg/m ³]	α [1/K]	T ₀ [K]	C [Pa]	ϕ	flow law	A [MPa ⁻ⁿ s ⁻¹]	n	E [kJ/mol]	V [m ³ /mol]
Sediments	1000	2.34	1.77e-6	2800	3e-5	293	1e6	8.6	Wet Quartzite ¹	3.2e-4	2.3	154	0
Upper crust	1000	2.34	1.75e-6	2800	3e-5	293	1e6	6.8	Quartzite ¹	6.7e-6	2.4	156	0
Lower crust	1000	1.97	2.5e-7	3000	3e-5	293	1e6	6.8*	Plagioclase (An 75) ^{2*}	3.3e-4	3.2	238	0
Lithosphere	1000	1.99	2.2e-8	3300	3e-5	293	1e6	28.68	Dry Olivine ³	2.5e4	3.5	532	17e-6
Asthenosphere	1000	1.99	2.2e-8	3300	3e-5	293	1e6	28.68	Dry Olivine ³	2.5e4	3.5	532	17e-6
Weak channel	1000	2	0	3300	3e-5	293	1e6	3.44*	Wet Olivine ⁴	2e3	4	471	0
Inclusion	1000	2	0	3000*	3e-5	293	1e6	36.9*	Mafic Granulite ⁵	1.4e4	4.2	445*	0

TABLE S1: Table of used Parameters. Parameters with an asterisk were varied. Reading from left to right: Phase: phase name that is used in the simulations, c_p [J/K]: heat capacity of the rock, k [W/(mK)]: conductivity of the rock, Q [W/m³]: radioactive heat generation, ρ_0 [kg/m³]: Density of the rock, α [1/K]: thermal expansion coefficient to compute the density of the rock, T₀ [K]: reference temperature used in the computation of the density, C [Pa]: Cohesion of the rock, ϕ : friction angle of the rock, flow law: used flow law for this rock, A [MPa⁻ⁿs⁻¹]: prefactor used in the viscosity computation, E [kJ/mol]: Activation energy used in the viscosity computation, V [m³/mol]: Activation volume used in the viscosity computation. Global parameters that were used: Adiabatic heating was used with $\alpha = 3e-5$, Gravity is set to 10 [m/s²], shear heating was used in all simulations except the reproduction of Li et al., 2010, ¹Ranalli and Murphy, 1987, ²Shelton and Tullis, 1981, ³Kirby, 1983, ⁴Ranalli, 1995, ⁵Wilks, 1990, Diabase rheology: Mackwell, 1998. Overall rheological parameters are assembled from Turcotte and Schubert, 2014, Li et al., 2010 and Bittner and Schmelting, 1995

	W_{inc} [km]	H_{inc} [km]	$MP(x)$ [km]	$MP(z)$ [km]	Shape	ϕ	$E [kJ]$	ρ [kg /m ³]	Plate vel	OP mean	OP exhume	OP max	OP %	extime [Ma]	Comments	
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion - L-shape	
IW_higher_5	-/-	-/-	-/-	10	-/-	-/-	-/-	-/-	0.2	0.4	0.5	60	~5	very fast exhumation - no subduction of incl.		
IW_lower_5	-/-	-/-	-/-	20	-/-	-/-	-/-	-/-	0.4	0.7	1.1	60	~14	break-off upper part exhumed		
IW_lower_8	-/-	-/-	-/-	23	cuboid	50°	-/-	-/-	0.45	1	1.2	60	~17.5	break-off - late exhumation upper part		
IW_lower_10	-/-	-/-	-/-	25	-/-	-/-	-/-	-/-	0.44	-	1.5	60	no	break-off - no exhumation		
IW_lower_15	-/-	-/-	-/-	30	-/-	-/-	-/-	-/-	0.61	-	1.6	60	no	break-off - no exhumation		
IW_strong	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.36	0.6	0.8	65	~10	no subduction of incl.		
IW_weak	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.36	0.6	0.8	65	~10	Inclusion flows in lower crust		
IW_WCfa15	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.7	0.9	0.9	50	~6	$\phi_{WC} = 15$ - no subduction of incl.		
IW_WCfa15.dI	-/-	-/-	-/-	20	-/-	-/-	-/-	-/-	0.6	1	1	50	~9	$\phi_{WC} = 15$ - no subduction of incl.		
IW_WCfa15.cr1	-/-	-/-	-/-	20	-/-	-/-	-/-	-/-	1	0.6	1	50	~25	$\phi_{WC} = 15$ - no subduction of incl.		
IW_WCfa20	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.6	0.8	0.8	50	~6	$\phi_{WC} = 20$ - no subduction of incl.		
IW_WCfa20.dII	-/-	-/-	-/-	20	-/-	-/-	-/-	-/-	0.6	0.7	0.7	50	~14	$\phi_{WC} = 20$ - no subduction of incl.		
IW_hfa_cub_I	-/-	-/-	-/-	22	cuboid	50	-/-	-/-	1.5	0.37	-	1.2	60	no	locking of subduction zone	
IW_hfa_sur45	-/-	-/-	-/-	27	cuboid	50	-/-	-/-	1.5	0.7	0.9	1.1	65	~5	$\phi_{LC} = 45$ - break-off	
IW_hfa_sur45_2	-/-	-/-	-/-	18	cuboid	50	-/-	-/-	1.5	0.6	0.7	0.9	60	~3	$\phi_{LC} = 45$ - break-off - strong topo	
IW_cuboid	-/-	-/-	-/-	-/-	cuboid	-/-	-/-	-/-	-/-	0.4	0.7	1.1	60	~9.6	break-off	
IW_high_fa	-/-	-/-	-/-	-/-	-/-	50	-/-	-/-	-/-	0.37	0.6	1	60	~12	complex bending of a large inclusion - L-shape	
IW_low_fa	-/-	-/-	-/-	-/-	-/-	25	-/-	-/-	-/-	0.3	0.4	0.5	60	~12	complex bending of a large inclusion - L-shape	
IW_e-150-10	-/-	-/-	2065	-/-	-/-	-/-	-/-	-/-	-/-	0.36	-	0.8	30	no	fast subduction of incl - almost no bending	
IW_sur45	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.8	0.9	1	70	~4.5	complex bending of a large inclusion - L-shape - strong topo	
Inclusion A	-/-	-/-	2020	-/-	-/-	-/-	-/-	-/-	-/-	0.3	0.5	1.2	60	~2.5	complex bending of a large inclusion - V-shape	
IW_150-10_1	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.37	0.9	0.95	65	~8	complex bending of a large inclusion - L-shape		
IW_150-10_h	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	3200	-/-	0.35	0.9	0.95	65	~15	complex bending of a large inclusion - L-shape
IA_cr1.5	-/-	-/-	2030	-/-	-/-	-/-	-/-	-/-	1.5	0.3	0.3	1.5	20	~36	complex bending of a large inclusion - V-shape	
IW_right_40	-/-	-/-	1960	-/-	-/-	-/-	-/-	-/-	0.3	0.8	0.97	60	~8	double bending of inclusion - huge influence of incl. on subduction		

	W _{inc} [km]	H _{inc} [km]	MP(x) [km]	MP(z) [km]	Shape	φ	E [kJ] /mol	ρ [kg/ m ³]	Plate vel	OP mean	OP exhume	OP max	OP %	exhume [Ma]	Comments
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion - L-shape
IW_left_20_2	-/-	-/-	1900	-/-	-/-	-/-	-/-	-/-	-/-	0.25	0.3	0.5	50	~12.5	no bending - no subduction of incl.
IW_cr1.5	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	1.5	0.33	0.9	0.9	65	~10	complex bending of a large inclusion - L-shape
IW_cr5	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	5	0.33	0.6	0.6	60	~25	complex bending of a large inclusion - L-shape
IA_d30	-/-	-/-	2030	30	-/-	-/-	-/-	-/-	0.6	-	1.4	30	no	complex bending of a large inclusion - V-shape - no exhumation	
IA_d40	-/-	-/-	2030	40	-/-	-/-	-/-	-/-	0.4	-	0.6	25	no	fast subduction of incl. - almost no bending	
IA_110_fa30	-/-	-/-	2020	-/-	-/-	-/-	-/-	-/-	0.4	0.3	1	40	~9	complex bending of a large inclusion - V-shape	
IA_110_12K	-/-	-/-	2020	-/-	-/-	-/-	-/-	-/-	-/-	0.4	-	1.1	35	no	12K geotherm - V-shape - no exhumation
IA_115	-/-	-/-	2015	-/-	-/-	-/-	-/-	-/-	-/-	0.4	0.3	1.3	30	~9	complex bending of a large inclusion - V-shape
IA_120	-/-	-/-	2010	-/-	-/-	-/-	-/-	-/-	-/-	0.4	1.2	1.2	35	~2.7	complex bending of a large inclusion - V-shape
IA_130	-/-	-/-	2000	-/-	-/-	-/-	-/-	-/-	-/-	0.4	1.2	40	~2.7	complex bending of a large inclusion - V-shape	
IA_150_15	-/-	15	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.32	0.4	0.9	60	~10	complex bending of a large inclusion - L-shape
IW_150_20	-/-	20	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.29	0.4	1	60	no	huge influence of incl. on subduction - L-shape
IW_left_5	-/-	20	1915	-/-	-/-	-/-	-/-	-/-	-/-	0.3	0.5	0.9	60	~11.5	complex bending of a large inclusion - L-shape
IW_left_10	-/-	20	1910	-/-	-/-	-/-	-/-	-/-	-/-	0.22	0.4	0.8	60	~11.5	only small piece subducts - L-shape
IW_left_20	-/-	20	1900	-/-	-/-	-/-	-/-	-/-	-/-	0.22	0.4	0.65	55	~11.5	no bending - no subduction of incl.
IW_right_5	-/-	20	1925	-/-	-/-	-/-	-/-	-/-	-/-	0.3	0.5	1.1	60	~17.5	complex bending of a large inclusion - L-shape
IW_right_10	-/-	20	1930	-/-	-/-	-/-	-/-	-/-	-/-	0.33	-	1	60	no	complex bending of a large inclusion - L-shape
IW_20_cr1.5	-/-	20	-/-	-/-	-/-	-/-	-/-	-/-	1.5	0.28	0.4	1.2	65	~6.5	huge influence of incl. on subduction - locking of subduction zone
IW_20_cr5	-/-	20	-/-	-/-	-/-	-/-	-/-	-/-	5	0.29	-	0.9	65	no	locking of subduction zone
IW_c_ll_cr1.5	-/-	20	-/-	17	cuboid	50	-/-	-/-	1.5	0.5	-	2	45	no	locking of subduction zone
IW_c_ll_cr1.5	-/-	20	-/-	18	cuboid	50	-/-	-/-	1.5	0.5	-	1.6	40	no	locking of subduction zone

	W_{inc} [km]	H_{inc} [km]	$MP(x)$ [km]	$MP(z)$ [km]	Shape	ϕ	$E [k]$ /mol]	ρ [kg /m ³]	Plate vel	OP mean	OP extreme	OP max	OP %	exhume	Comments	
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion	
IW_150_25	-/-	25	-/-	-/-	-/-	-/-	-/-	-/-	0.3	0.4	1.1	60	~13	huge influence of inclusion on subduction - less bending of incl. - L-shape		
IW_c.II2_cr1.5	-/-	25	-/-	17	cuboid	50	-/-	-/-	1.5	0.5	-	1.3	40	no	locking of subduction zone	
IW_c.dl2_cr1.5	-/-	25	-/-	18	cuboid	50	-/-	-/-	1.5	0.5	-	1.3	40	no	locking of subduction zone	
IA_10_2	10	2	1980	-/-	-/-	-/-	-/-	-/-	-/-	0.05	0.1	0.1	0	5	no influence of incl.	
IA_20_2	20	2	1990	20	-/-	-/-	-/-	-/-	-/-	0.15	-	0.3	0	no	no influence of incl. - subduction of incl.	
IA_20_2.g10K	20	2	1990	40	-/-	-/-	-/-	-/-	2800	1.5	0.05	-	0.1	0	no	10K geotherm - no influence of incl. - no subduction process
IW_20_5.r20	20	5	1940	35	-/-	-/-	-/-	-/-	-/-	0.6	-	0.8	40	no	inclusion stays at the subduction neck	
IW_20_5.r30	20	5	1950	35	-/-	-/-	-/-	-/-	-/-	0.6	-	0.8	40	no	inclusion subducts completely	
IW_20_5.r40	20	5	1960	35	-/-	-/-	-/-	-/-	-/-	0.6	-	0.8	40	no	inclusion subducts completely	
IW_20_10	20	10	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.17	0.1	0.2	50	~7	fast exhumation - no bending	
IW_c.sl_cr1.5	20	10	-/-	17	cuboid	50	-/-	-/-	1.5	0.1	0.1	0.2	40	~17.5	large aspect ratio - low OP	
IW_c.sL_cr1.5	20	10	-/-	17	cuboid	50	-/-	-/-	1.5	0.1	0.1	0.2	40	~17.5	large aspect ratio - low OP	
IW_c_circle	20	20	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.17	0.2	0.2	50	~4.5	fast exhumation - no bending	
IW_square	20	20	-/-	-/-	cuboid	-/-	-/-	-/-	-/-	0.15	0.2	0.2	50	~4.5	fast exhumation - no bending	
IA_30_3	30	3	1980	20	-/-	-/-	-/-	-/-	1	0.4	-	0.7	20	no	$\phi_{WC} = 10 - \text{complex bending o. small I.}$	
IA_30_3.f15	30	3	1980	20	-/-	-/-	-/-	-/-	-/-	1	0.4	-	0.7	20	no	$\phi_{WC} = 15 - \text{complex bending o. small I.}$
IA_30_3.f20	30	3	1980	20	-/-	-/-	-/-	-/-	1	0.4	-	0.7	20	no	$\phi_{WC} = 20 - \text{complex bending o. small I.}$	
IA_30_3.d	30	3	1980	30	-/-	-/-	-/-	-/-	1	0.3	-	0.6	20	no	$\phi_{WC} = 15 - \text{complex bending o. small I.}$	
IA_30_3_A	30	3	1970	20	-/-	-/-	-/-	-/-	1	0.3	-	0.5	30	no	$\phi_{WC} = 15 - \text{complex bending o. small I.}$	
IA_40_4	40	4	1980	20	-/-	-/-	-/-	-/-	1	0.3	-	0.6	30	no	$\phi_{WC} = 40 - \text{complex bending o. small I.}$	
IA_50_5	50	5	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.2	-	0.4	50	no	12K geotherm - Diabase rheology lower crust	
IA_50_5_g11K	50	5	1961	22	-/-	-/-	-/-	-/-	-/-	0.1	0.4	0.4	30	~14	11K geotherm - Diabase rheology lower crust	
IA_s150	50	5	1961	18	-/-	-/-	-/-	-/-	-/-	0.8	0.8	0.8	100	~10	$\phi_{LC} = 30 - \text{L-shape}$	
IA_50_5_g10K	50	5	1961	18	-/-	-/-	-/-	-/-	-/-	0.7	-	0.9	30	no	10K geotherm - Diabase rheology lower crust - $\phi_{LC} = 30 - \text{L-shape}$ - locking of subduction zone	

	W_{inc} [km]	H_{inc} [km]	$MP(x)$ [km]	$MP(z)$ [km]	Shape	ϕ	E [kJ /mol]	ρ [kg $/m^3$]	Pl_{vol} [cm/a]	OP mean	OP exhume	OP max	OP %	extime [Ma]	Comments
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion - L-shape
IA_60.6_d1	60	6	2030	13	-/-	-/-	-/-	-/-	-/-	0.25	0.3	0.3	25	~13	small bending of incl. - no subduction of incl.
IA_60.6_d2	60	6	2050	13	-/-	-/-	-/-	-/-	-/-	0.4	-	0.6	10	no	fast subduction of incl. - bending of incl. in the mantle
IA_60.6_sC	60	6	1980	22	-/-	-/-	-/-	-/-	-/-	0.7	-	1	50	no	$\phi_{LC} = 30$ - fast subduction of incl.
IA_60.8	60	8	1950	18	-/-	-/-	-/-	-/-	-/-	0.05	0.1	0.1	25	~8	12K geotherm - Diabase rheology lower crust - no subduction of incl.
IA_80.6	80	6	1920	25	-/-	-/-	-/-	-/-	-/-	0.4	-	0.6	50	no	12K geotherm - Diabase rheology lower crust
IA_100.6	100	6	-/-	25	-/-	-/-	-/-	-/-	-/-	0.3	-	0.9	0	no	12K geotherm - Diabase rheology lower crust - L-shape
IA_100.6_120	100	6	1970	22	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~8	Diabase rheology lower crust - V-shape
IA_100.6_110	100	6	1980	22	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~11	Diabase rheology lower crust - V-shape
IA_100.6_120_g9K	100	6	1970	22	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~12	9K geotherm - Diabase rheology lower crust - V-shape
IA_100.6_110_g9k	100	6	1980	22	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~13	9K geotherm - Diabase rheology lower crust - V-shape
IA_100.6_120_d1	100	6	1970	23	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~12	Diabase rheology lower crust - V-shape
IA_100.6_110_d1	100	6	1980	23	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~13	Diabase rheology lower crust - V-shape
IA_100.6_120_d2	100	6	1970	23	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~13	9K geotherm - Diabase rheology lower crust - V-shape
IA_100.6_110_d2	100	6	1980	22	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1	35	~14	9K geotherm - Diabase rheology lower crust - V-shape
IA_100.8	100	8	-/-	25	-/-	-/-	-/-	-/-	-/-	0.4	-	0.9	0	no	12K geotherm - Diabase rheology lower crust - L-shape
IA_100.9_h	100	9	1990	22	-/-	-/-	-/-	-/-	-/-	0.5	-	>1.2	30	no	Diabase rheology lower crust - 9K geotherm - V-shape - incl. close to surface
IA_100.9_h2	100	9	1990	22	-/-	-/-	-/-	-/-	-/-	0.6	-	>1.2	30	no	Diabase rheology lower crust - 9K geotherm - V-shape - incl. close to surface
IA_100.9_r10_h	100	9	2000	22	-/-	-/-	-/-	-/-	-/-	0.6	-	>1.2	30	no	Diabase rheology lower crust - 9K geotherm - V-shape - incl. completely subducts
IA_100.9_r10_h2	100	9	2000	22	-/-	-/-	-/-	-/-	-/-	0.6	-	>1.2	30	~11	Diabase rheology lower crust - 9K geotherm - V-shape - incl. completely subducts

	W_{inc} [km]	H_{inc} [km]	$MP(x)$ [km]	$MP(z)$ [km]	Shape	ϕ	E [kJ /mol]	ρ [kg /m ³]	P_{vel} [cm/a]	OP mean	OP exhumation	OP max	OP %	exhumation [Ma]	Comments	
<hr/>																
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion	
IA_100_9_h3	100	9	1990	22	-/-	45	-/-	-/-	-/-	0.5	0.3	>1.2	35	~12	Diabase rheology lower crust - V-shape	
IA_100_9_r10_h3	100	9	2000	22	-/-	45	-/-	-/-	-/-	0.7	-	>1.2	35	no	Diabase rheology lower crust - V-shape - incl. completely subducts	
IA_100_9_r10_h4	100	9	2000	22	-/-	50	-/-	-/-	-/-	0.7	-	>1.2	35	no	Diabase rheology lower crust - V-shape - incl. completely subducts	
IA_100_9_h4	100	9	1990	22	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~12	Diabase rheology lower crust - V-shape	
IA_100_9_21_h	100	9	1980	21	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~8	Diabase rheology lower crust - 8K geotherm - V-shape	
IA_100_9_21_h2	100	9	1980	21	-/-	50	-/-	-/-	-/-	0.5	0.4	>1.2	35	~5	Diabase rheology lower crust - 9K geotherm - V-shape	
IA_x1990	100	9	1990	22	-/-	45	-/-	-/-	-/-	0.6	0.9	0.9	60	~12	Diabase rheology lower crust - 9K geotherm - V-shape	
IW_hfa_cub	100	-/-	-/-	22	cuboid	50	-/-	-/-	-/-	1.5	0.3	0.8	1	50	~23	break-off - upper part exhumed
IW_100_10	100	-/-	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.24	0.4	0.5	60	~10	very fast exhumation - no subduction of incl.	
IW_100_10-d1	100	-/-	2030	13	-/-	-/-	-/-	-/-	-/-	0.3	0.5	0.5	35	~10	no subduction of incl.	
IW_100_10_d2	100	-/-	2030	21	-/-	-/-	-/-	-/-	-/-	0.3	-	0.6	10	no	fast subduction of incl.	
IW_100_15	100	15	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.22	0.4	0.5	50	~10	very fast exhumation - no subduction of incl.	
IW_100_20	100	20	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.21	0.4	0.4	30	~10	very fast exhumation - no bending	
IA_120_8	120	8	1970	-/-	-/-	-/-	-/-	-/-	-/-	0.6	0.6	0.6	50	~10	11K geotherm - Diabase rheology lower crust - no subduction of incl.	
IA_120_8_g11K	120	8	1970	20	-/-	-/-	-/-	-/-	-/-	0.35	0.1	0.8	30	~10	11K geotherm - Diabase rheology lower crust - no subduction of incl. - upwards bending	
IA_120_10_g11K	120	10	-/-	20	-/-	-/-	-/-	-/-	-/-	0.5	0.5	0.5	40	~10	11K geotherm - Diabase rheology lower crust - L-shape	
IA_120_10_g11K	120	10	-/-	25	-/-	-/-	-/-	-/-	-/-	0.5	-	0.5	40	no	11K geotherm - Diabase rheology lower crust - L-shape - locking of subduction zone	
IA_120_10_g13K	120	10	-/-	18	-/-	-/-	-/-	-/-	-/-	0.1	0.4	0.4	35	~8	13K geotherm - Diabase rheology lower crust - no subduction of incl.	
IA_120_10_g13K	120	10	1930	-/-	-/-	-/-	-/-	-/-	-/-	0.2	0.4	0.4	40	~8	13K geotherm - Diabase rheology lower crust - no subduction of incl.	
IA_120_10_110	120	10	1970	20	-/-	-/-	-/-	-/-	-/-	0.5	0.2	0.9	30	~11	Diabase rheology lower crust - no subduction of incl. - upwards bending	

	W _{inc} [km]	H _{inc} [km]	MP(x) [km]	MP(z) [km]	Shape	φ	E [kJ] /mol	ρ [kg/m ³]	P _{vel} [cm/a]	OP mean	OP exhume	OP max	OP %	exhume [Ma]	Comments
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion - L-shape
IA_120_10_hfa	120	10	1970	20	-/-	45	-/-	-/-	-/-	0.3	0.4	0.9	30	~10	9K geotherm - Diabase rheology lower crust - complex bending of a large inclusion - V-shape
IH_x1950	120	10	1950	20	-/-	-/-	-/-	-/-	-/-	0.4	0.6	0.6	100	~10	11K geotherm - Diabase rheology lower crust - complex bending of a large inclusion - V-shape
IH_20_x1920	120	10	1920	20	-/-	45	-/-	-/-	-/-	0.6	1.1	1.1	60	~13	11K geotherm - Diabase rheology lower crust - complex bending of a large inclusion - V-shape
IA_120_11_g9K_h3	120	11	1980	21	-/-	-/-	-/-	-/-	-/-	0.5	0.4	>1.2	35	~4	Diabase rheology lower crust - 9K geotherm - V-shape
IA_120_11_g9K_h4	120	11	1980	21	-/-	55	-/-	-/-	-/-	0.5	0.4	>1.2	35	~5	Diabase rheology lower crust - 9K geotherm - V-shape
IA_120_11_g10K_h	120	11	1980	21	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	45	~4	Diabase rheology lower crust - 10K geotherm - V-shape
IA_120_11_g10K_h2	120	11	1980	21	-/-	55	-/-	-/-	-/-	0.6	0.4	>1.2	35	~4	Diabase rheology lower crust - 10K geotherm - V-shape
IA_120_11_g9K_h	120	11	1980	22	-/-	45	-/-	-/-	-/-	0.6	0.4	>1.2	35	~10	9K geotherm - Diabase rheology lower crust - V-shape
IA_120_11_g9K_h2	120	11	1980	22	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~7	9K geotherm - Diabase rheology lower crust - V-shape
IA_120_11_h	120	12	1980	22	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~7	Diabase rheology lower crust - V- shape
IA_120_11_h2	120	12	1980	22	-/-	55	-/-	-/-	-/-	0.6	0.4	>1.2	35	~7	Diabase rheology lower crust - V- shape
IA_120_11_g10K_h2	120	11	1980	21	-/-	55	-/-	-/-	-/-	0.6	0.4	>1.2	35	~4	10K geotherm - Diabase rheology lower crust - V-shape
IA_120_12_h	120	12	1970	22	-/-	45	-/-	-/-	-/-	0.35	0.4	0.8	30	~12	Diabase rheology lower crust - complex bending of a large inclusion - V-shape
IA_120_12_h2	120	12	1980	22	-/-	40	-/-	-/-	-/-	0.3	0.2	0.85	25	~8	Diabase rheology lower crust - com- plex bending of a large inclusion - V-shape
IA_120_12_h3	120	12	1980	22	-/-	30	-/-	-/-	-/-	0.25	0.1	0.7	25	~7	complex bending of a large inclusion - V-shape
IA_120_12_h5	120	12	1980	22	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~12	Diabase rheology lower crust - V- shape - incl. completely subducts
IA_120_12_h6	120	12	1980	22	-/-	55	-/-	-/-	-/-	0.6	0.4	>1.2	35	~12	Diabase rheology lower crust - V- shape - incl. completely subducts

	W_{inc} [km]	H_{inc} [km]	$MP(x)$ [km]	$MP(z)$ [km]	Shape	ϕ	E [kJ] /mol	ρ [kg /m ³]	P_{vel} [cm/a]	OP mean	OP exhume	OP max	OP %	exhume [Ma]	Comments
IW_reference	150	10	1920	15	elliptical	36.9	445	3000	3	0.36	0.8	0.9	60	~10	complex bending of a large inclusion
IA_120_12-gOK_h	120	12	1980	21	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~9	Diabase rheology lower crust - V-shape
IA_120_12-gOK_h	120	12	1980	21	-/-	50	-/-	-/-	-/-	0.6	0.4	>1.2	35	~4	10K geotherm - Diabase rheology lower crust - V-shape
IA_120_12_10.1	120	12	1980	22	-/-	30	-/-	-/-	-/-	0.5	0.5	>1.2	45	~10	Diabase rheology lower crust - V-shape - coesite field reached
IA_120_12_10_LC	120	12	1980	22	-/-	30	-/-	-/-	-/-	0.7	-	1	30	no	Diabase rheology lower crust - ϕ_{LC} = 20 - V-shape - incl. completely subducts
Strong LC	120	12	2000	22	-/-	30	-/-	-/-	-/-	0.4	-	0.9	50	no	Diabase rheology lower crust - ϕ_{LC} = 30 - V-shape - incl. breaks
IA_120_12_10_LC2	120	12	1980	22	-/-	30	-/-	-/-	-/-	0.8	-	1	30	no	Diabase rheology lower crust - ϕ_{LC} = 20 - V-shape - incl. completely subducts
IA_120_12_10	120	12	1980	22	-/-	40	-/-	-/-	-/-	0.5	0.5	>1.2	40	~7.4	Diabase rheology lower crust - V-shape - coesite field reached
Strong inclusion	120	12	2000	22	-/-	30	-/-	-/-	-/-	0.6	1.2	>1.2	60	~8	V-shape - coesite field reached
IA_140_12	140	12	-/-	23	-/-	-/-	-/-	-/-	-/-	0.4	-	1	30	no	12K geotherm - Diabase rheology lower crust - L-shape - locking of subduction zone
IW_c_d15_cr1.5	200	-/-	-/-	-/-	cuboid	50	-/-	-/-	-/-	1.5	0.4	-	1.3	50	no
IW_e-200_10	200	-/-	2065	-/-	-/-	-/-	-/-	-/-	-/-	0.4	-	1	30	no	fast subduction of incl - almost no bending
IW_e-200_15	200	15	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1.1	50	~7	fast complex bending of a huge inclusion - L-Shape
IW_e-200_20	200	20	-/-	-/-	-/-	-/-	-/-	-/-	-/-	0.6	0.5	1.1	50	~12	complex bending of a huge inclusion - L-Shape

TABLE S2: Table of results of performed simulations. Reading from left to right: W_{inc} [km]: width of the inclusion in km, H_{inc} [km]: height of the inclusion in km, $MP(x)$ [km]: midpoint of the inclusion in x direction in km, $MP(z)$ [km] : midpoint of the inclusion in z in km Shape: shape of the inclusion (can be elliptical, cuboid or circular), ϕ : friction angle used for the inclusion, E [kJ /mol]: activation energy used in the dislocation creep rheology for the inclusion, ρ [kg /m³], P_{vel} [cm/a]: prescribed compression velocity of the plate in cm/a, OP mean: average overpressure observed in the whole inclusion in GPa, OP exhume: average exhumed overpressure of the inclusion, that was observed during the runtime of the simulation in GPa, OP max: average maximum overpressure observed in the inclusion in GPa, OP %: average percentage of overpressure with respect to the dynamic pressure, exhume [Ma]: approximated time after which the first part of the inclusion is exhumed to the surface, Comments: short description of either special parameters that where used, distinctive evolutionary shape of the inclusion or special deformation patterns. The nomenclature for the simulations originates from a combination of the position of the inclusion in the domain (f.e. IA = (1)inclusion (A) above the subduction channel), the x-y-position (f.e. 100_6_d1 = inclusion with a width of 100 km and a height of 6 km in a non-reference depth) and special additional cases (like a non-reference geotherm). Abbreviations: -/-: same value as the reference simulation, incl.: inclusion, WC: weak channel, LC: Lower crust